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# CARA: Collision-Aware Rate Adaptation for IEEE 802.11 WLANs

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# Outline

- Introduction
- Automatic Rate Fallback
- Collision-Aware Rate Adaptation
- Performance Evaluation
- Conclusion

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# Introduction

- IEEE 802.11 provide **multiple transmission rates** to maximize the system performance.
  - e.g. 802.11b: 1, 2, 5.5, 11 Mbps
- Rate adaptation schemes
  - Closed-loop approaches
    - The **receiver** specifies its desired transmission rate and feeds back to the transmitter.
  - Open-loop approaches
    - A **transmitter** makes the rate adaptation decision solely based on its local **Acknowledgement** information.

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# Introduction (cont.)

- Automatic Rate Fallback (ARF)
  - A **simple open-loop rate adaptation scheme**, is implemented on most of the commercial device.
  - A key problem:
    - They do not consider **malfunction severely when many transmission failures are due to collisions**.

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# ARF in IEEE 802.11

- Operations:

- When missing Ack frames:

- it alternates the transmission rates by keeping track of a timing function.

- If two consecutive Acks are not received correctly:

- The second retry and the subsequent transmissions are done at a lower transmission rate.
    - And a timer is started.

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# ARF in IEEE 802.11 (cont.)

- When either the **timer expires** or the number of **successfully-received Acks** reaches 10:
  - The transmission rate is raised to the next higher transmission rate.
  - And the timer is cancelled.
- If an Ack is not received for the very next data frame:
  - The transmission rate is lowered again.
  - And the timer is restarted.

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# Collision-Aware Rate Adaptation (CARA)

- One salient feature of CARA:
  - It is able to **differentiate collisions from channel errors** at the transmitter side without any help/feedback from the receiver station.
  
- CARA specifies two methods:
  - RTS Probing
  - CCA Detection (Optional)

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# RTS Probing

- **RTS/CTS:**
  - **Assumptions:**
    - Transmission error probability of an RTS frame is negligible.
    - All the RTS transmission failures are due to collisions.
  - **Collision or channel error detection:**
    - A data transmission failure following a successful RTS/CTS exchange must be due to channel errors.
    - Unnecessary rate decrements are completely avoided.

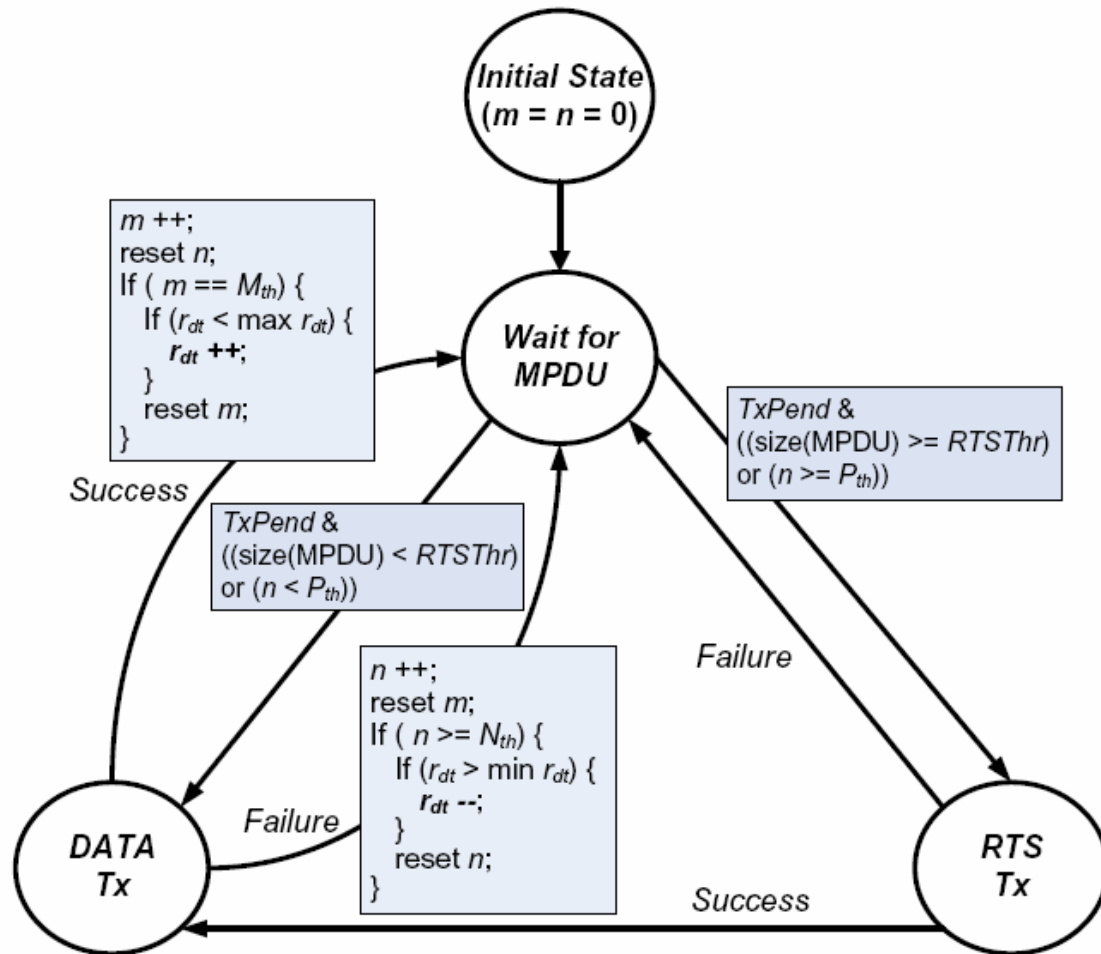


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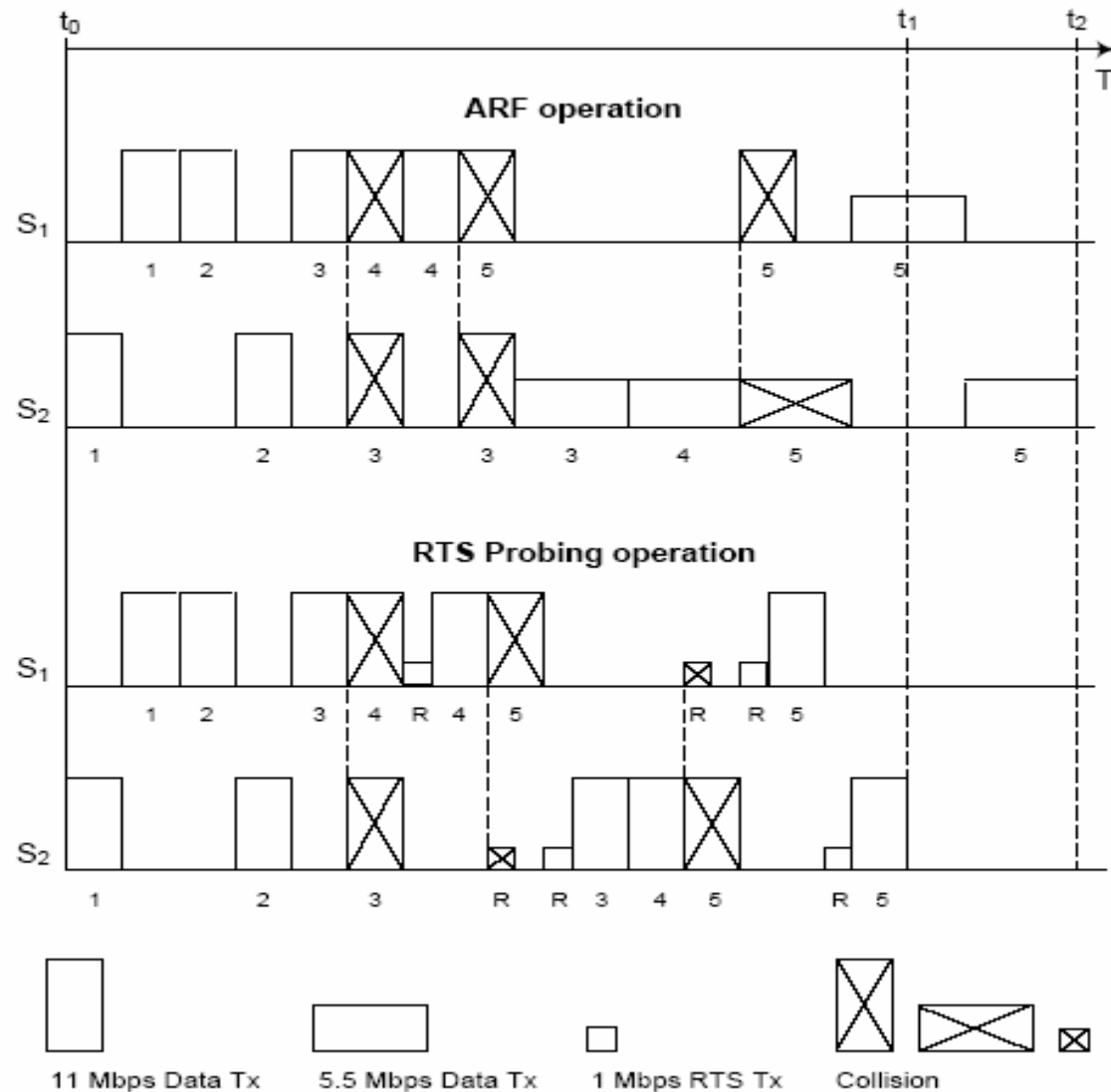
# RTS Probing (cont.)

- ❑ Effect:
  - The added RTS/CTS overhead.
  - In fact, the RTS/CTS option is disabled in most 802.11 products.
- RTS Probing:
  - ❑ Enables RTS/CTS exchange only when a data frame transmission fails.

# State Transition Diagram of RTS Probing



# Example of RTS Probing



# CCA Detection

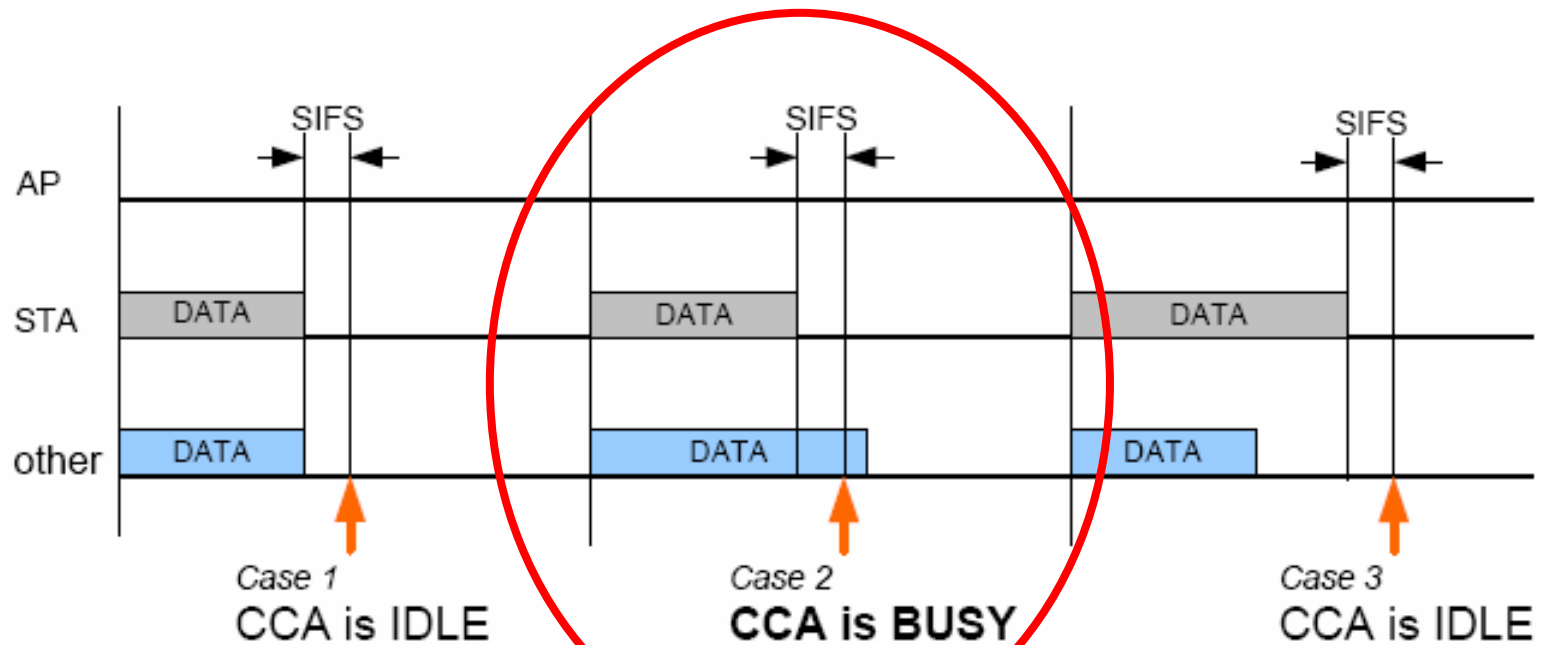
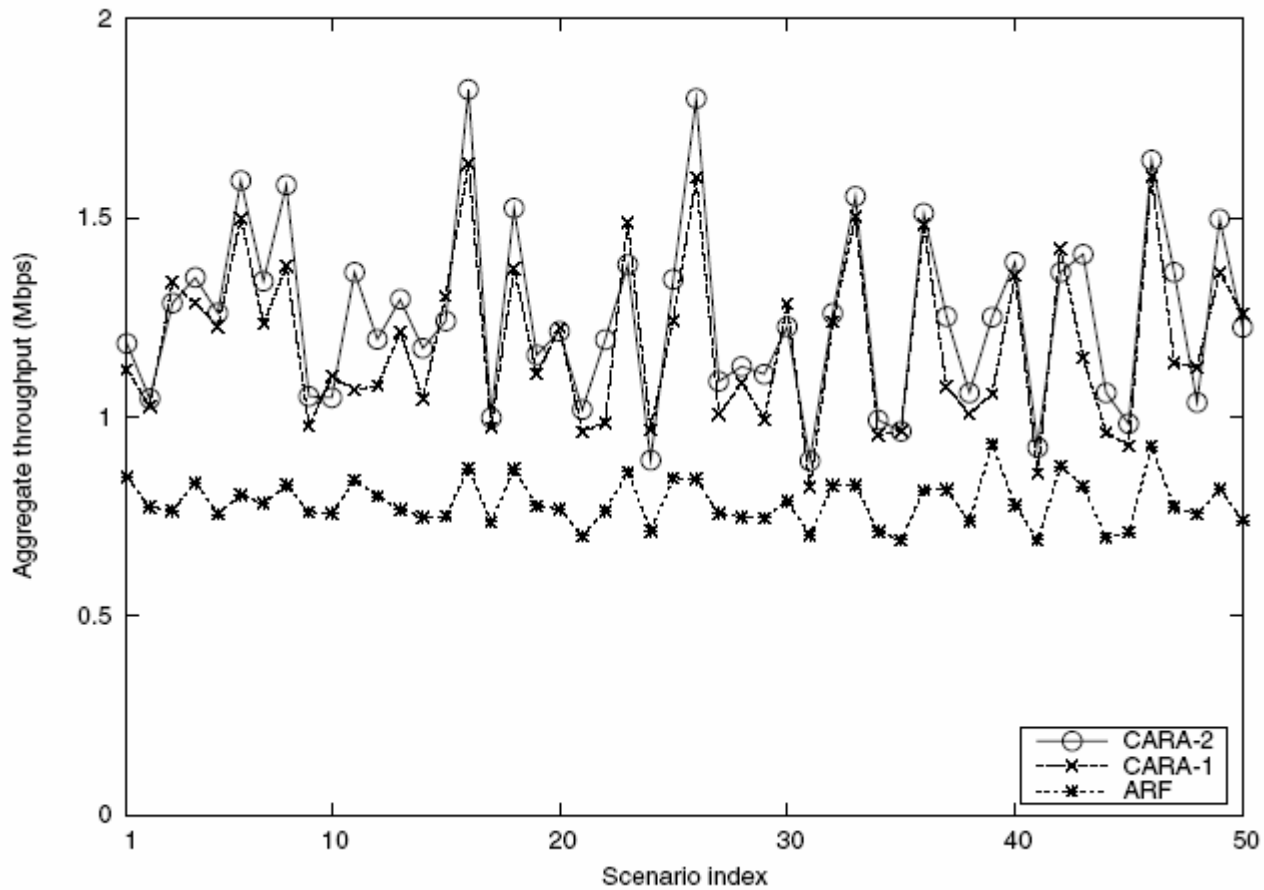


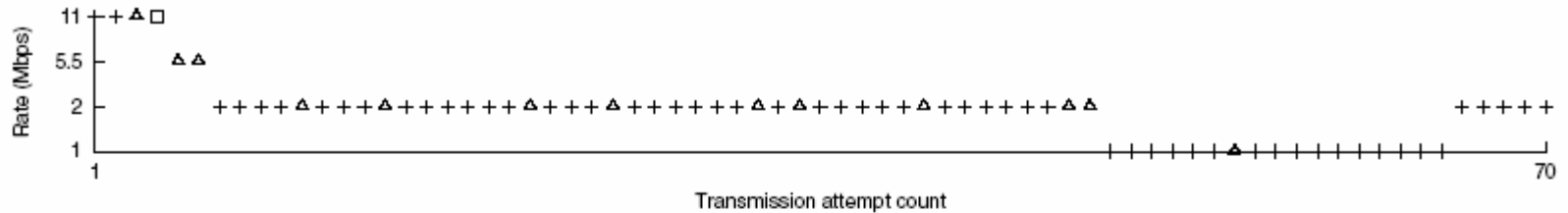
Fig. 5. Three possible cases of collision. In the second case, the collision can be detected via CCA detection.

CCA: Clear Channel Assessment

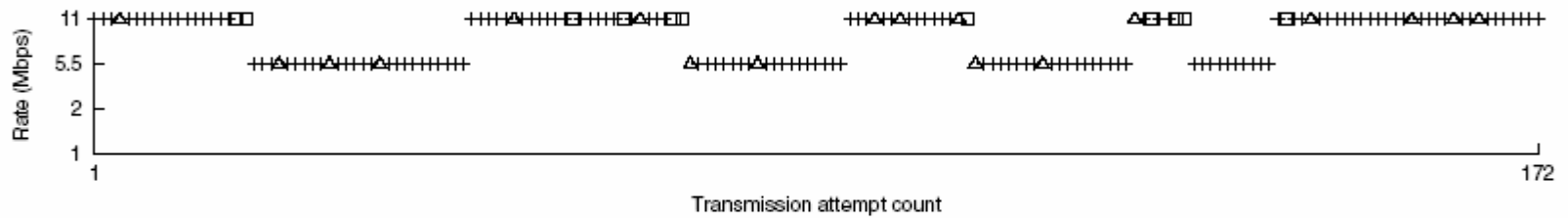
# Performance



# Comparison



(a) ARF



(b) CARA-1



+	Success	Δ	Collision
□	Channel error	▽	Collision detected by CCA Detection

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# Conclusions

- The key idea of CARA is that the transmitter station combines **adaptively** the RTS/CTS exchange with the CCA functionality to differentiate **frame collisions** from frame transmission failures caused by **channel errors**.
- Therefore, compared with ARF, CARA is more likely to make the correct rate adaptation decisions.

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## Conclusions (cont.)

- Moreover, CARA does not require any change to the current 802.11 standard, thus facilitating its deployment with existing 802.11 devices.