Message Efficient Time Synchronization in Wireless Sensor Networks

Presented by L. C. Chen July. 12, 2007

Outline

- Introduction
- Related Works
- Network Model
- Time Synchronization Scheme
- Time Synchronization Scheme in heterogeneous network
- Simulation
- Conclusion

Introduction(1)

- Time synchronization is an important problem in wireless sensor networks.
- A lot of operation needs it.
 - Data aggregation
 - TDMA schedules
 - Synchronized sleep
 - Periods
- Most of time synchronization methods in traditional internet and wireless LAN do not consider the limited resourced.

Introduction(2)

- This protocol uses overhearing concept and multi-hop architecture suitable for WSN.
- We use bi-directional links to do two-way synchronization.

Relative offset

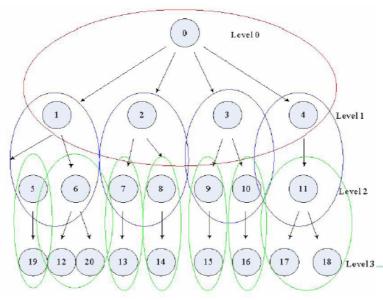
Through every node maintains an individual clock, these clocks are not synchronized with respect to each other.

Relative drift

□ Timers between two nodes are not exactly the same.

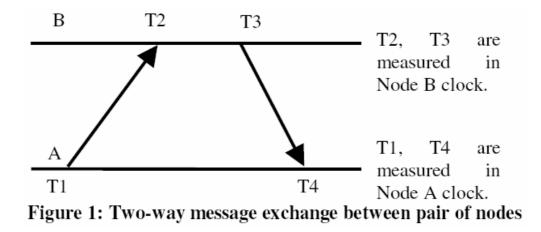
Related works-NTS[1]

- Through creating a spanning tree, all the nodes are connected with one another.
- The concept of subtree makes the whole synchronization process be divided into multiple repeated sub-processes.
- NTS didn't adapt to the situation of mobility nodes.



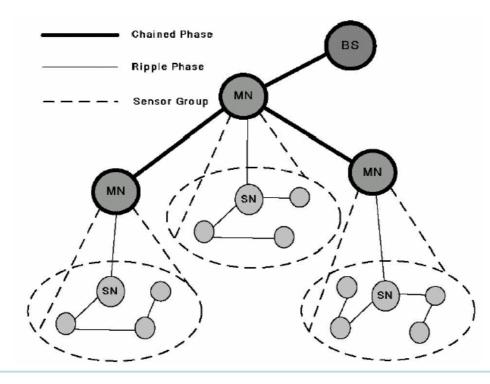
Related works-TPSN[2]

- TPSN is based on the simplistic approach of conventional senderreceiver time synchronization.
- TPSN need execute "level discovery phase" before initiating the "synchronization phase".



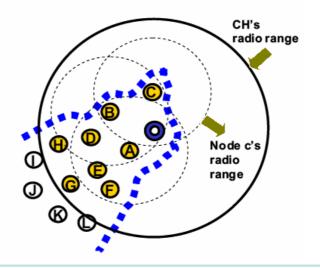
Related works-CRIT[3]

- CRIT contributes in the accurate hierarchical and multi-hop time synchronization with low error-rate and efficient clock offset.
- They didn't discuss the detail about how to build the architecture.



Related works-CHTS[4]

- CHTS introduced the hierarchical clustering protocol to decrease the synchronization error by reducing the average hop count from the reference node to each node.
- They didn't discuss the detail about the architecture of "CH layer".

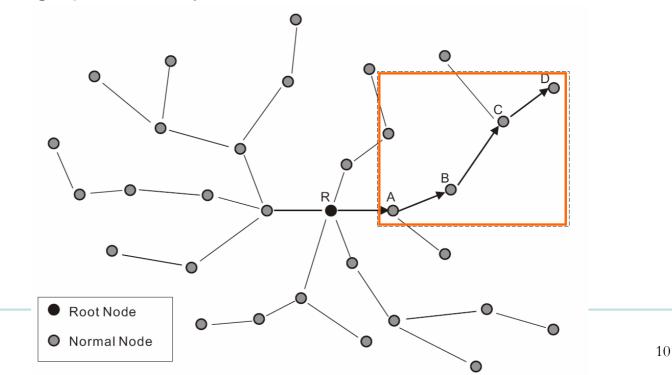


Network Model

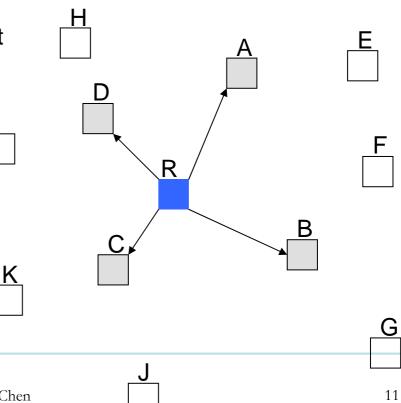
- There are N sensor nodes in a rectangle area.
- Every sensor node has a location (x,y).
- We determine that the transmission range is a constant R.
- There are three states for nodes :
 - General state
 - Preparative state
 - Synchronized state

Network Model

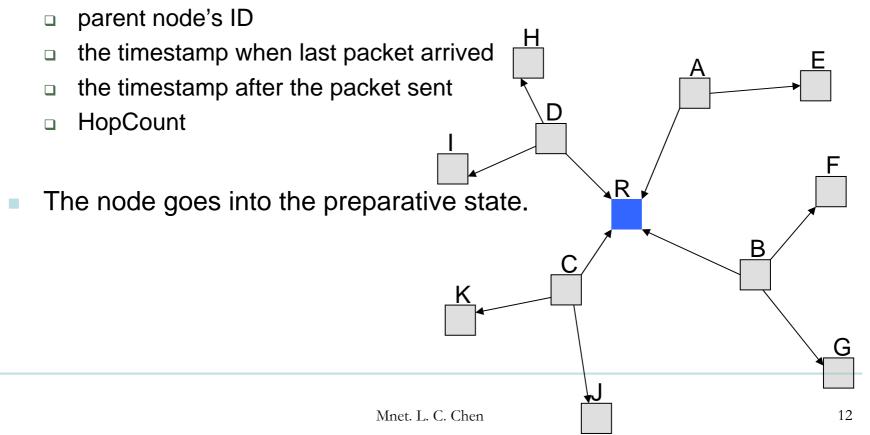
- The reference node like sink in network manages the time synchronization for all of nodes in environment acted as the gateway between the sensor network and the external world.
- After the wireless sensor network is deployed, root node floods a beacon message periodically.



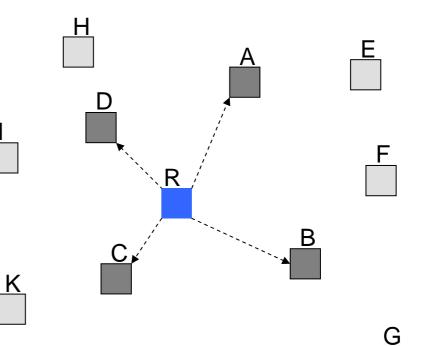
- At the beginning of a round, all nodes are in the general state except for reference node.
- The reference node floods a snotify_packet to begin a round.
 - □ ID
 - the timestamp after this packet sent
 - HopCount



- After the node receives this packet, the node also floods its snotify_packet.
 - ID



- When the parent node receives the snotify_packet from the nodes, it will calculate the offset for the node.
- The parent node is in the synchronized state, it will waits for some time to collect all the information from the children nodes and then floods a soffset_packet.
 - ID
 - all of the children node's ID
 - all of the children node's offset



If the node receives the snotify_packet from the node when it is in the synchronized state, it can calculate the offset for the children node by equation (1).

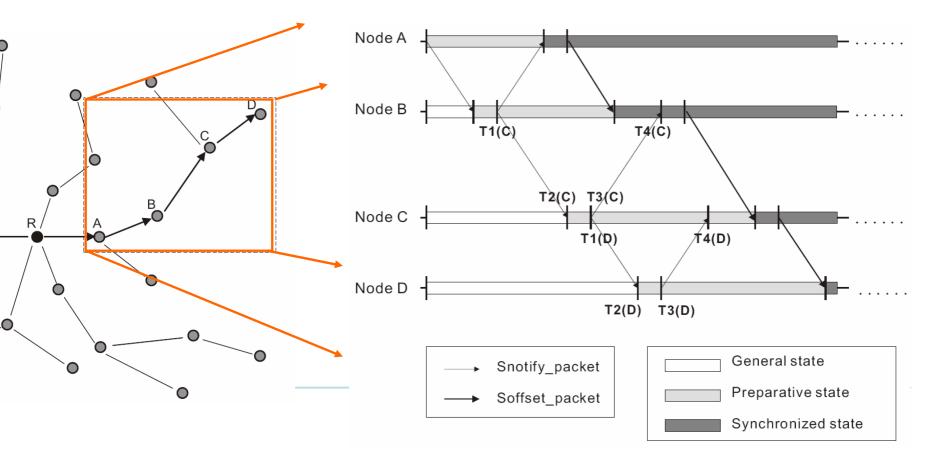
(1) Offset(X) = {(T4(X) - T3(X))-[T2(X) -(offset(parent's ID) + T1(X))]}/ 2

If the node receives the snotify_packet from the node when it is in the preparative state, we will calculate the offset by equation (2).

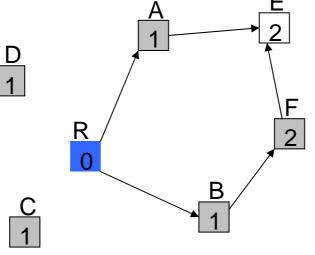
(2) Offset(X) = [(T4(X) - T3(X)) - (T2(X) - T1(X))]/2 + offset(parent's ID)

Offset(C) = {(T4(C) - T3(C))-[T2(C) - (offset(B) + T1(C))]}/2

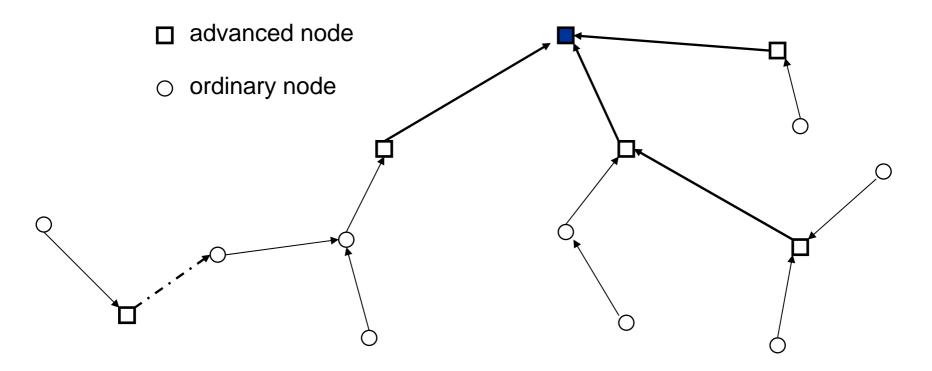
Offset(D) = [(T4(D) - T3(D)) - (T2(D) - T1(D))]/2 + offset(C)



- If a node in the preparative state or the synchronized state receives the second *snotify_packet*, we will compare these two *HopCounts*.
- If the HopCount in the snotify_packet is less than that in the node, the node will record the information of the snotify_packet serving as the reference for next round.



In order to reduce the error, we provide an algorithm for decreasing hop counts through the clustering of nodes.

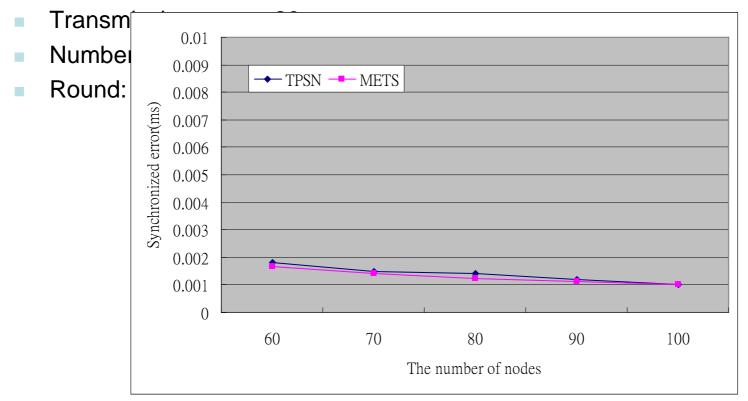


- We add a parameter Advanced_HopCount to make advanced nodes as close to the reference nodes as possible to achieve the result of decreasing the hop count.
- When an advanced node wants to flood its *snotify_packet*, it will increase an *Advanced_HopCount* to record the hop counts among those advanced nodes in its packet.

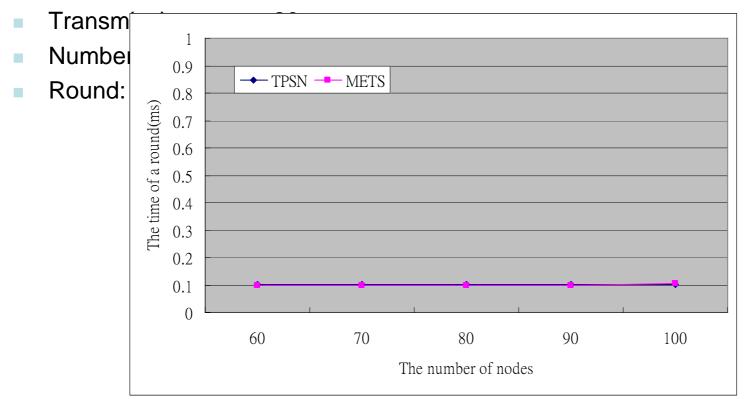
- snotify_packet for advanced nodes:
 - ID
 - parent node's ID
 - the timestamp when last packet arrived
 - the timestamp after the packet sent
 - HopCount
 - Advanced_HopCount
- snotify_packet for ordinary node:
 - ID
 - parent node's ID
 - the timestamp when last packet arrived
 - the timestamp after the packet sent
 - HopCount

- If a node receives a snotify_packet excluding the Advanced_HopCount parameter, it will execute according to the scheme of the above.
- If we both have Advanced_HopCount and HopCount information, we compare the value of Advanced_HopCount first. The node will select the node of smaller Advanced_HopCount to be its parent.
- Only if two packets have the same value of Advanced_HopCount, we choose the value of HopCount to decide the parent.

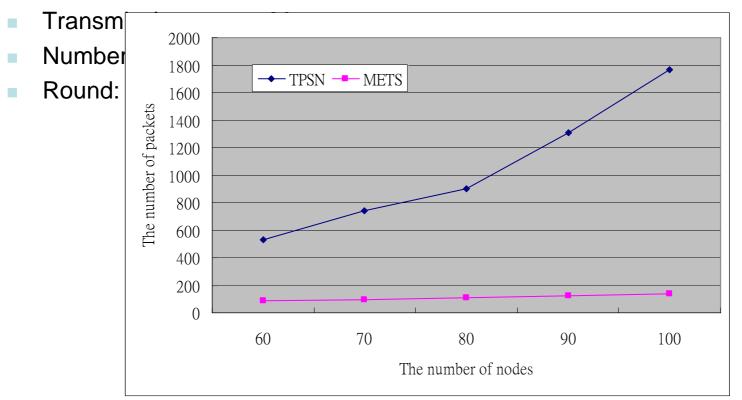
Simulation(1)



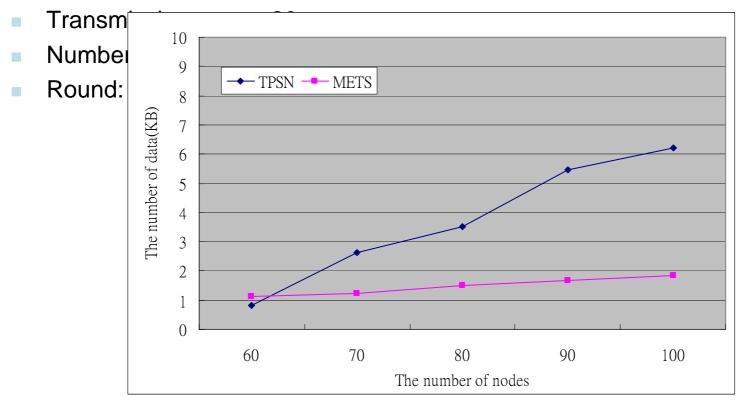








Simulation(4)



Conclusion

- We introduce a simple, flexible, energy-efficient, and always-on time synchronization called METS for wireless sensor networks.
- METS utilizes the concept of overhearing to decrease the transmission message for calculating the clock values.
- Through the simulations, METS certainly save a lot of power through.
- The algorithm also adapts to heterogeneous wireless sensor network.

References

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