



# Congestion Avoidance Based on Lightweight Buffer Management in Sensor networks

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A blue header banner with a world map on the left and a fiber optic cable on the right. The word "Introduction" is centered in white text.

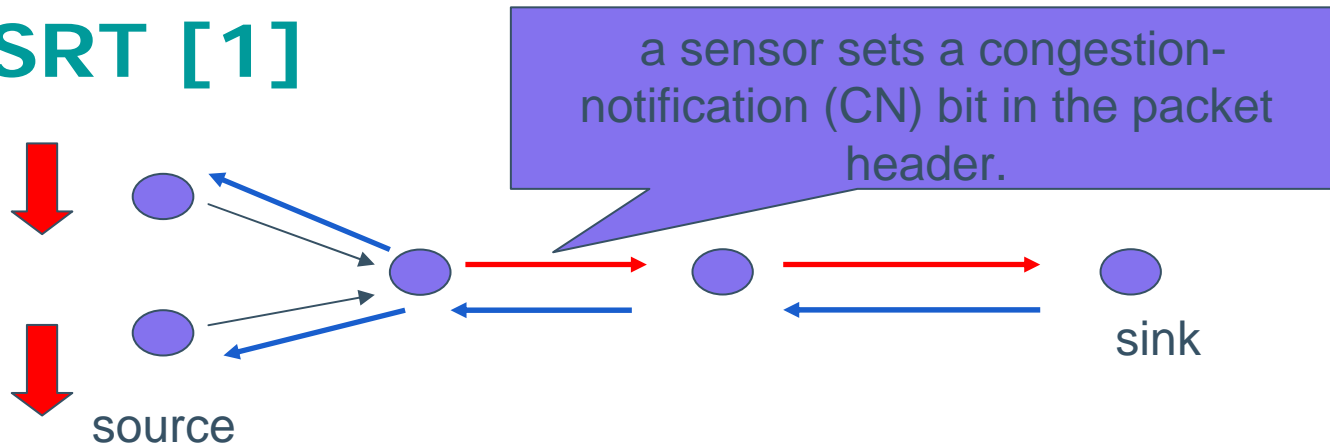
# Introduction

- ❖ When a sensor receives more data than it can forward, the excess data has to be buffered.
- ❖ **Congestion** occurs when the limited data has to be buffered.
- ❖ **Congestion control** studies how to recover from a congestion.
- ❖ **Congestion avoidance** studies how to prevent congestion from happening.

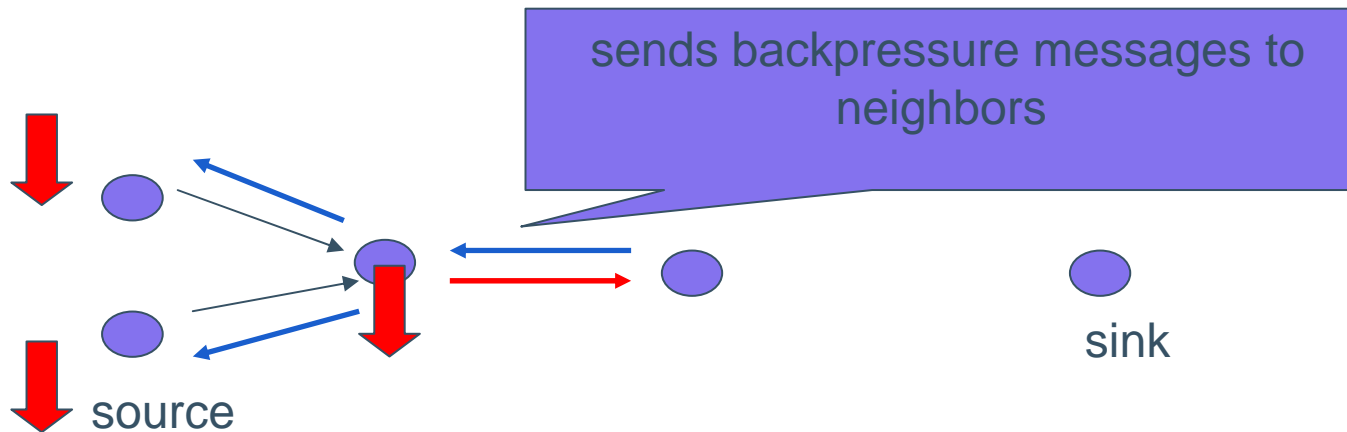
# Related Work

## Rate-based Congestion Control

### ❖ ESRT [1]



### ❖ CODA [2]





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## Buffer-Based Congestion Avoidance

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The header of the slide features a blue background with a stylized world map on the left and a fiber optic cable on the right. The title "Network Model" is centered in white text.

# Network Model

- ❖ A sensor network consists of a set of sensors and a set of base stations (also called sinks).
- ❖ There exists a neighbor discovering protocol.
- ❖ There exists a MAC protocol, e.g. based on CSMA.
- ❖ The sensors are statically located after deployment.
- ❖ It makes no difference which particular sink a packet is delivered.
- ❖ All data packets have the same size.

A blue header banner with a world map on the left and a fiber optic cable on the right. The title 'Basic Scheme' is centered in white text.

## Basic Scheme

- ❖ The key for congestion avoidance is to make sure that a sensor  $y$  sends a packet to another sensor  $x$  only when  $x$  has the buffer space to hold the packet.
- ❖ To keep the neighbors of  $x$  updated with the  $x$ 's buffer size, whenever  $x$  sends out a packet, it piggybacks its current buffer state in the frame header.

A blue header banner with a world map on the left and a fiber optic cable on the right. The title 'Basic Scheme' is centered in white text.

# Basic Scheme

- ❖ Consider a sensor  $y$  that is one of the neighbor sensors of  $x$ .
  - When  $y$  receives or overhears a packet to forward  $x$ , **it caches the buffer state of  $x$ .**
  - Only if  $x$ 's buffer is not full,  $y$  forwards the packet. Otherwise,  **$y$  withholds the packet until it overhears a packet from  $x$ , piggybacking a nonfull buffer state.**





## **Implement the Basic Scheme with Various MAC Protocols.**

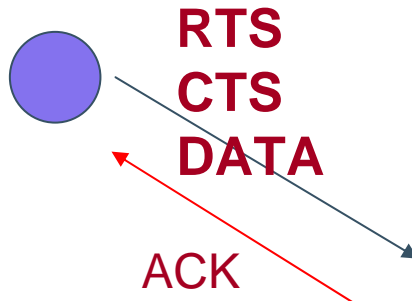


# CSMA/CA and CSMA with ACK

- ❖ Data transmission requires RTS-CTS-DATA-ACK exchange between two neighboring sensors.
- ❖ One bit in each packet is used to piggyback whether the sender's buffer is full.
- ❖ When a sensor  $y$  that is the neighbor sensor of  $x$  overhears a frame from  $x$ , it caches the residual-buffer size of  $x$ .
- ❖ Only if  $x$ 's buffer is not full,  $y$  forwards the packet. Otherwise

# CSMA/CA and CSMA with ACK

a's residual  
buffer=0



a's residual  
buffer=0



a's residual  
buffer=1

collision

# CSMA with Implicit ACK

- ❖ When the media contention level is not high ,CSMA can be reduced to DATA packets only for the purpose of energy efficiency.
- ❖ One approach of implementing implicit ACK is for data packets to carry an one-byte acknowledgement field in their headers



A blue header banner with a world map on the left and a white antenna on the right. The title 'CSMA with Implicit ACK' is centered in white text.

# CSMA with Implicit ACK

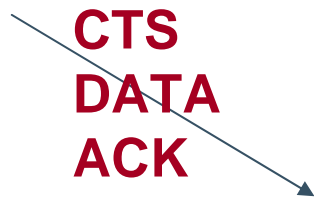
- ❖ When a sensor  $x$  sends out a DATA packet. It piggybacks its residual-buffer in the frame header.
- ❖ When a sensor  $y$  that is the neighbor sensor of  $x$  overhears a frame from  $x$ , it caches the residual-buffer size of  $x$ .
- ❖ When  $y$  overhears a packet that is sent by another sensor to  $x$ , it reduces the residual-buffer size of  $x$  by one.

## CSMA/CA and CSMA with ACK

a's residual  
buffer=1



**RTS**  
**CTS**  
**DATA**  
**ACK**



a's residual  
buffer=0



a's residual  
buffer=0

## CSMA with implicit ACK

a's residual  
buffer=1



**DATA**



a's residual  
buffer=0



a's residual  
buffer=0

# The Hidden-terminal problem of CSMA with implicit ACK

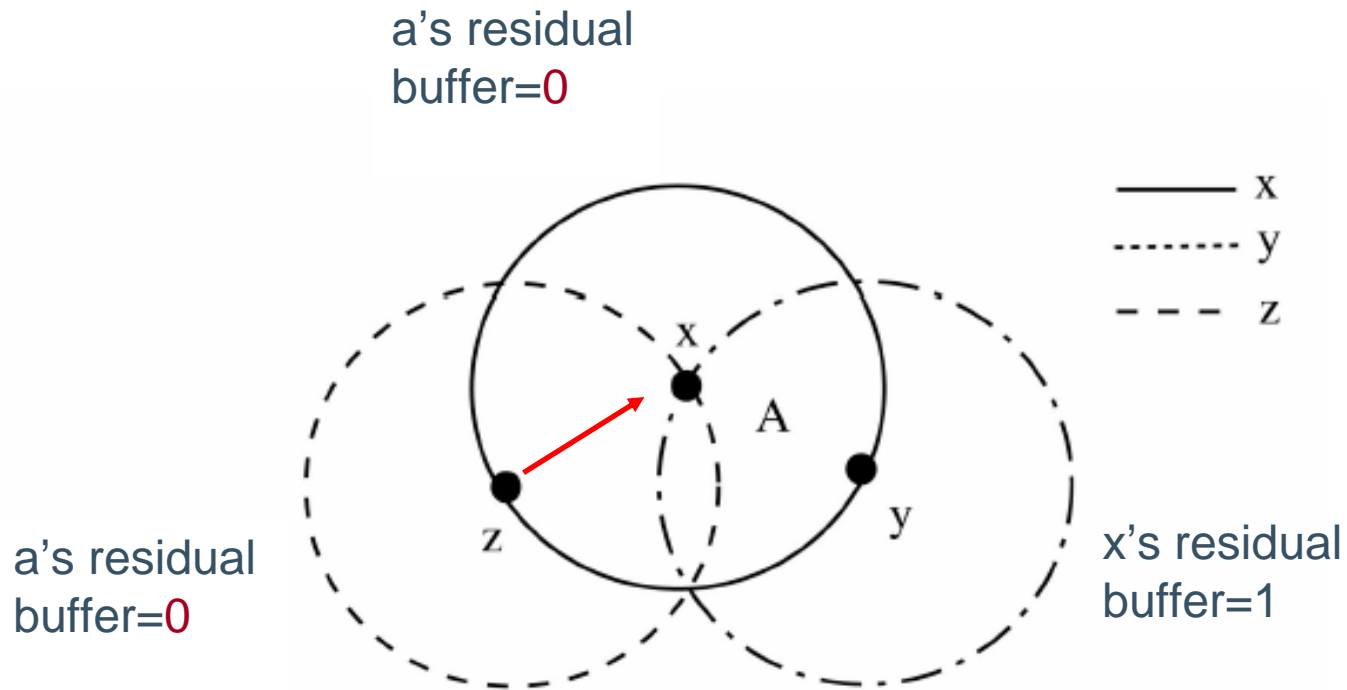
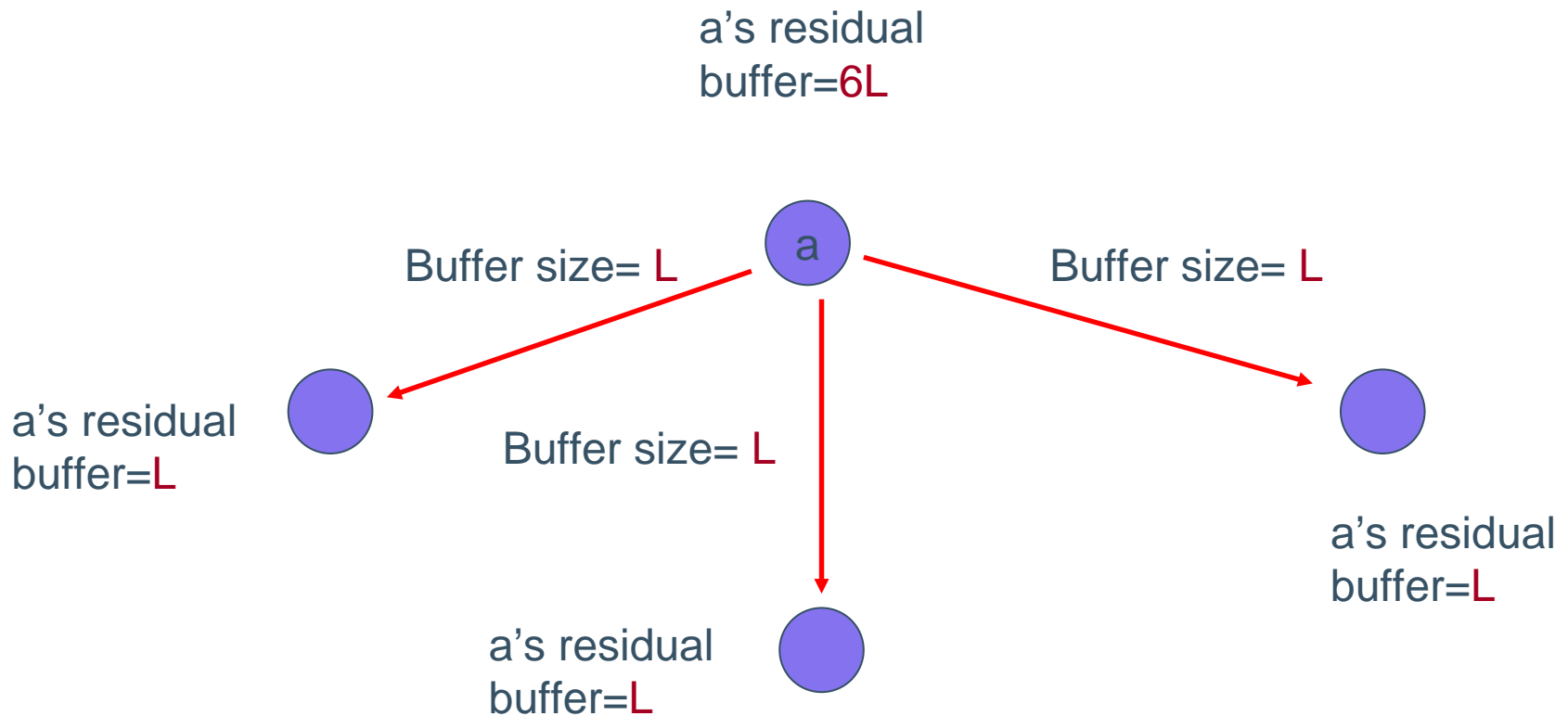


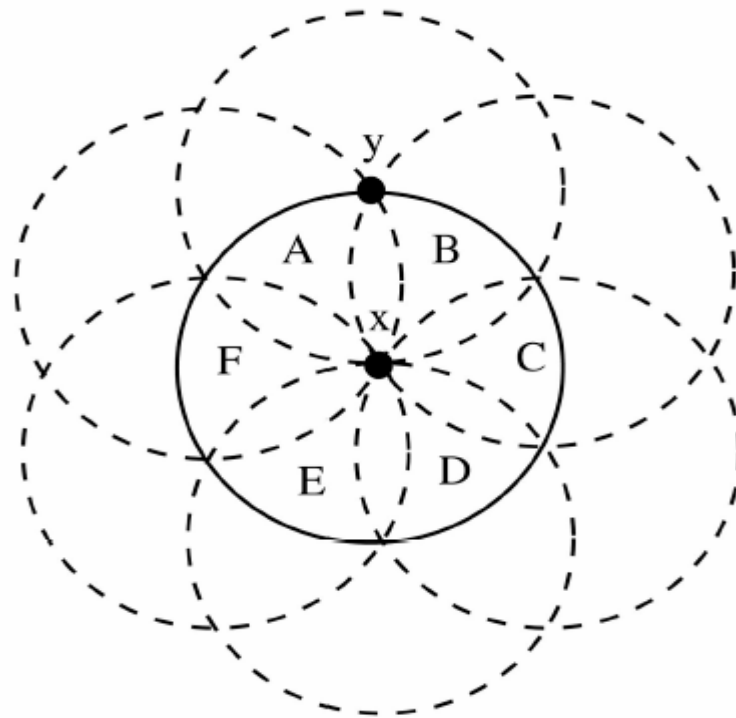
Fig. 2. Hidden-terminal problem.

# 1/6-buffer Solution for the Hidden-terminal problem





**Theorem 1.** *Suppose all sensors have the same circular transmission range. Hidden terminals do not cause buffer congestion when the  $1/6$ -buffer solution is used.*



A blue header banner with a white world map on the left and a white antenna on the right. The title 'Adaptive 1/k-buffer Solution' is written in white text across the center.

# Adaptive 1/k-buffer Solution

- ❖ **In reality, the radio transmission range is highly irregular.**
- ❖ **To handle the general case, an adaptive 1/k-buffer solution is used.**



# Adaptive 1/k-buffer Solution

- ❖ If there is no buffer overflow for a long time, the sensor concludes that  $K$  is set too conservatively and it **reduces**  $k$  by one.
- ❖ Whenever there is buffer overflow, the sensor knows that  $K$  is set too aggressively and it **increases**  $k$  by one.
- ❖ The idea is to dynamically adjust  $k$  to **a minimum value** that does not cause buffer overflow.



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# **Simulation Results**

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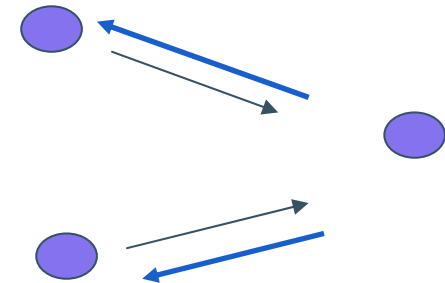
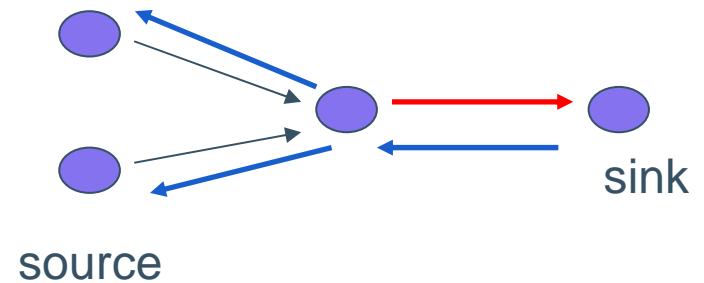
❖ **The following four congestion control/avoidance schemes are implemented:**

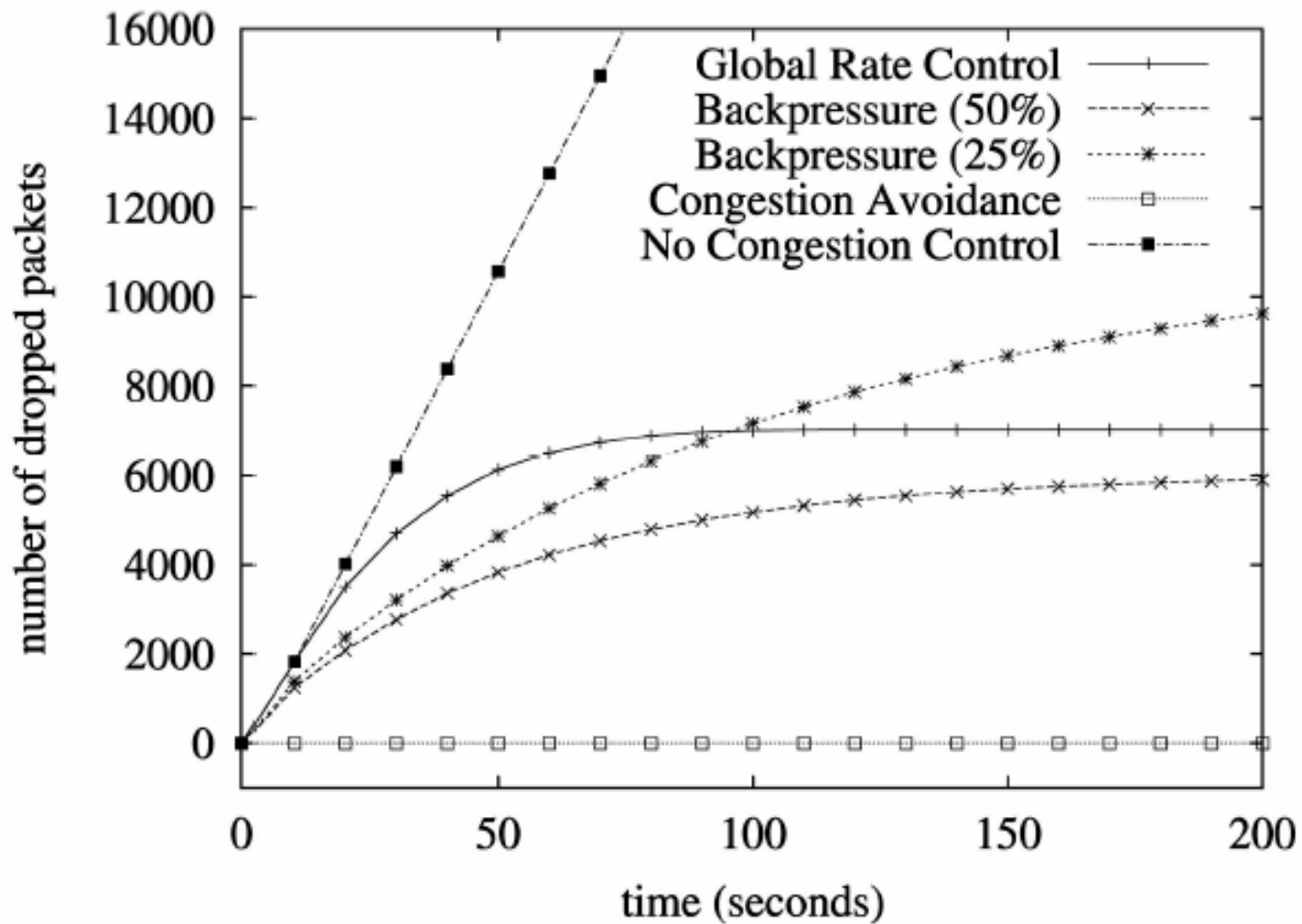
- Global Rate Control

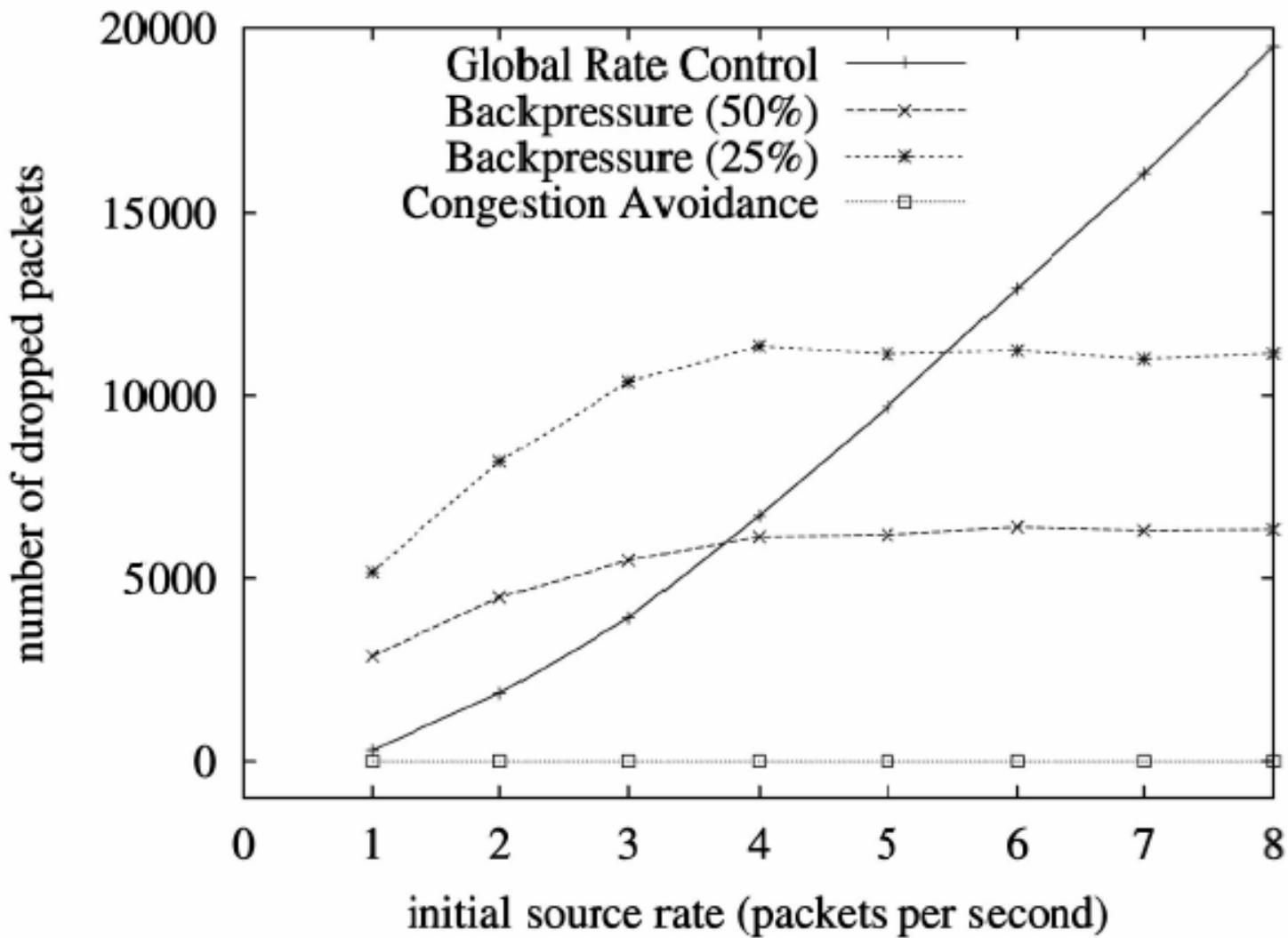
- Backpressure

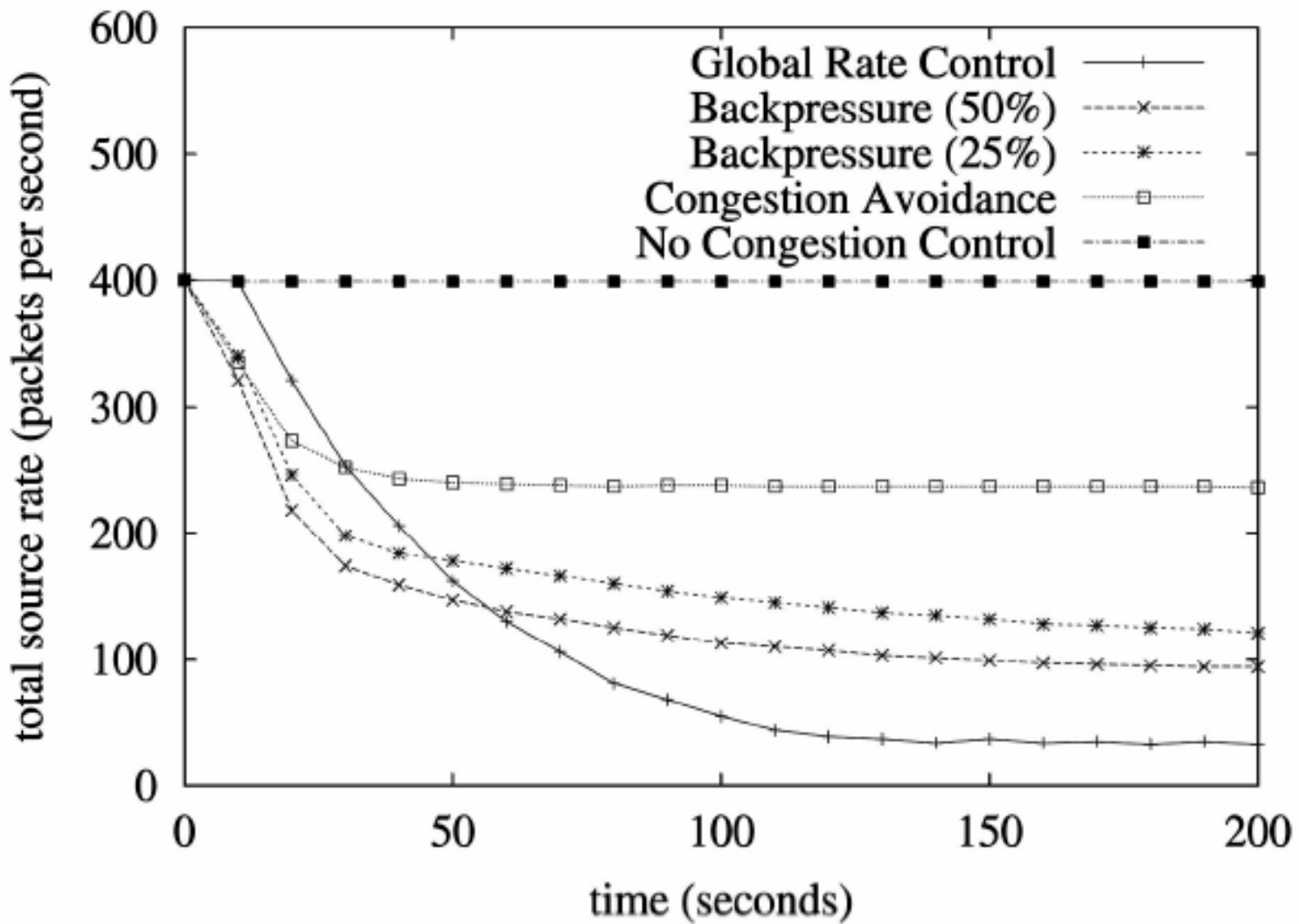
- Congestion avoidance

- No congestion control

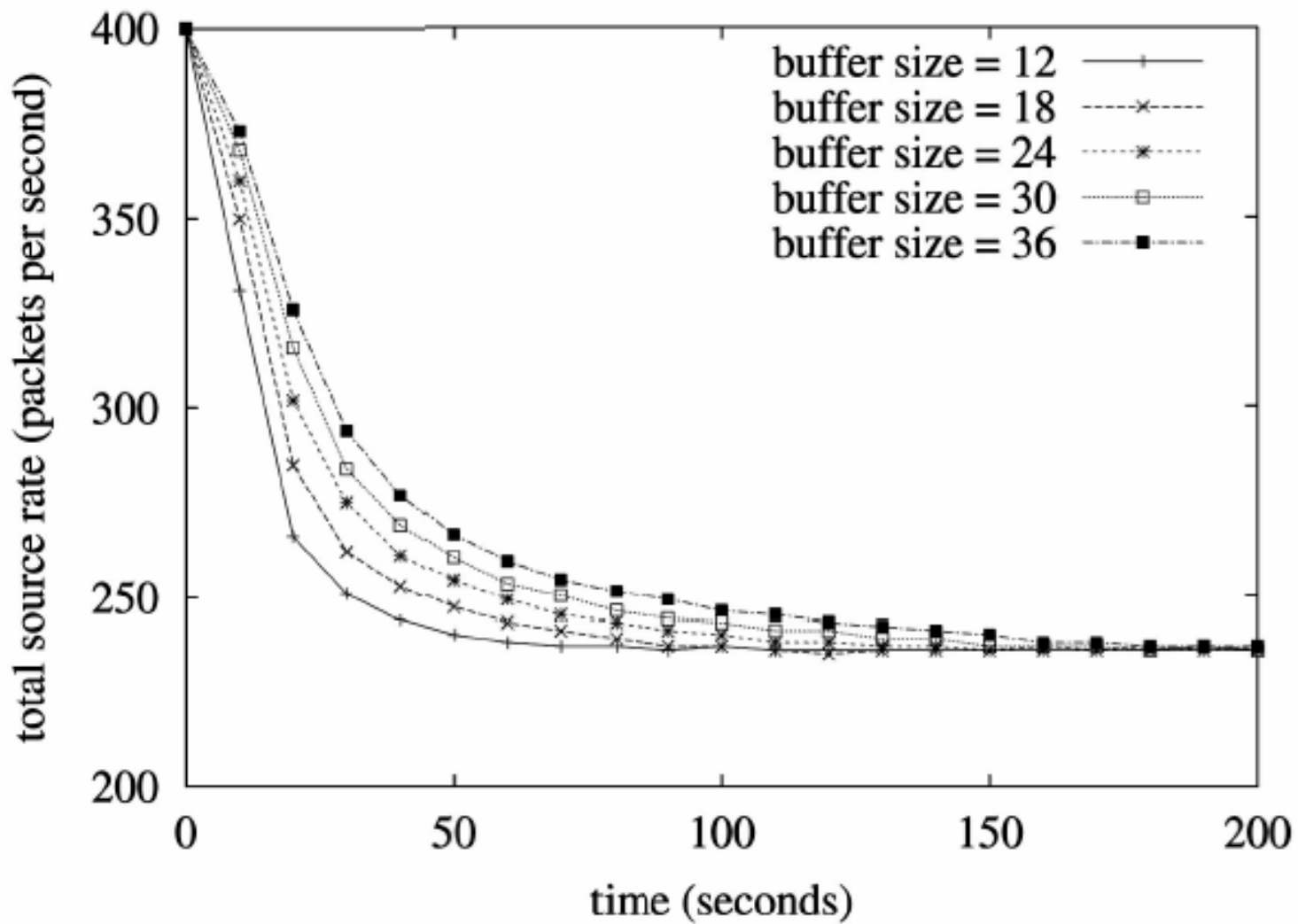




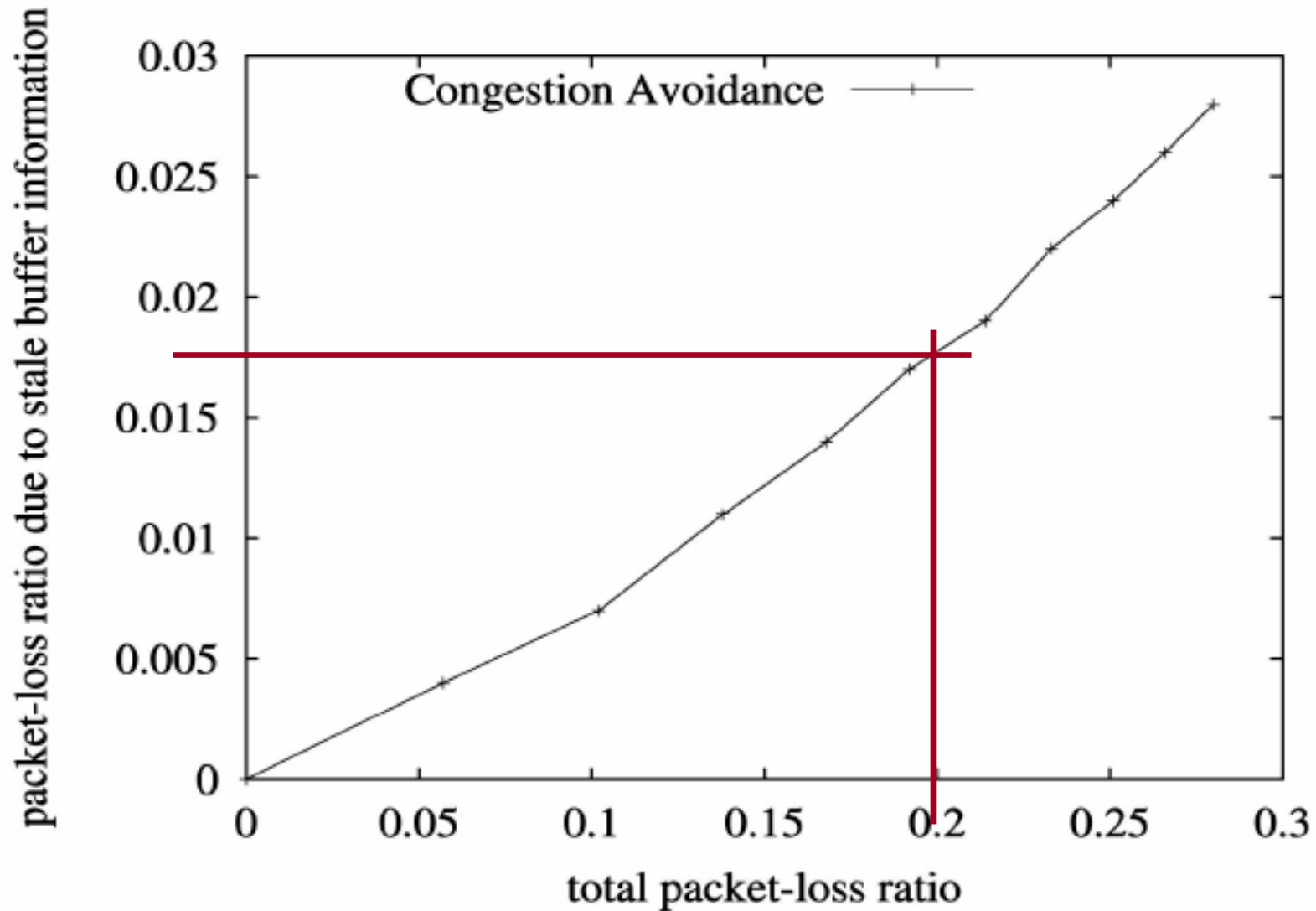








# Impact of Failed Overhearing



# Conclusion

- ❖ **This paper proposes a buffer-based congestion avoidance scheme.**
- ❖ **It shows how to implement such a scheme with various MAC protocol.**
- ❖ **For CSMA with implicit ACK, the  $1/k$ -buffer solution for the hidden-terminal problem is proposed.**

# References

- ❖ [1] Y. Sankarasubramaniam, O. Akan, and I. Akyildiz, "ESRT: Eventto-Sink Reliable Transport in Wireless Sensor Networks," Proc.Fourth ACM Symp. Mobile Ad Hoc Networking and Computing(MobiHoc '03), June 2003.
- ❖ [2] C.-Y. Wan, S.B. Eisenman, and A.T. Campbell, "CODA: Congestion Detection and Avoidance in Sensor Networks," Proc. ACM SenSys '03, Nov. 2003.

The background features a 3D globe on the left side, with a magnifying glass positioned over it. Several satellite-like components are attached to the globe's surface. The background is a vibrant blue with horizontal white lines, and a large, faint circular graphic is visible on the right. The bottom of the image is divided into a blue horizontal band and a green horizontal band.

**Thank You !**