
Cost and Collision Minimizing Forwarding Schemes for Wireless Sensor Networks

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Outline

- Introduction
- Related work
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- Simulation results
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- Discussions

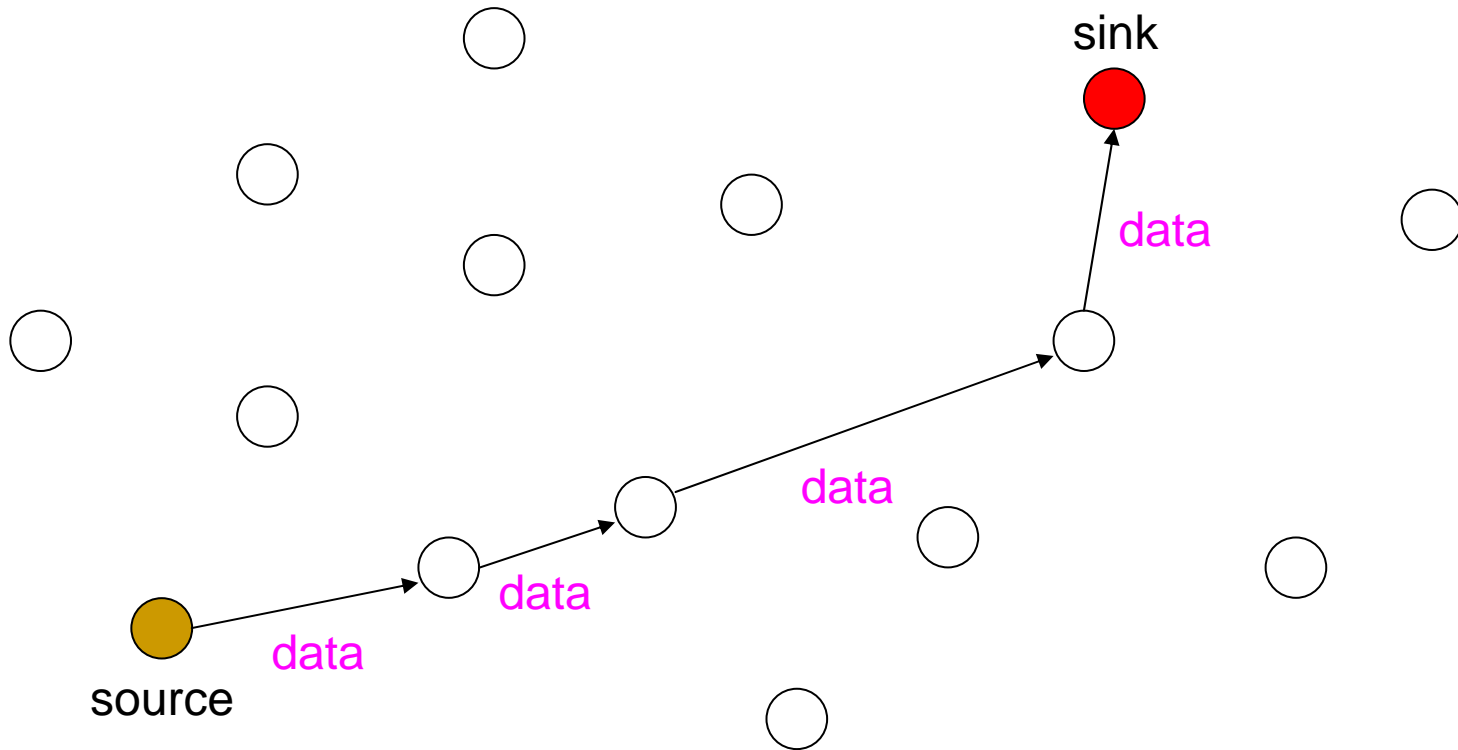
Introduction(1/2)

- Forwarding operation is commonly used for WSNs.
 - Sensor nodes are resource constrained
 - Efficient in energy consumption
 - Efficient in the quality of the paths from source to sink

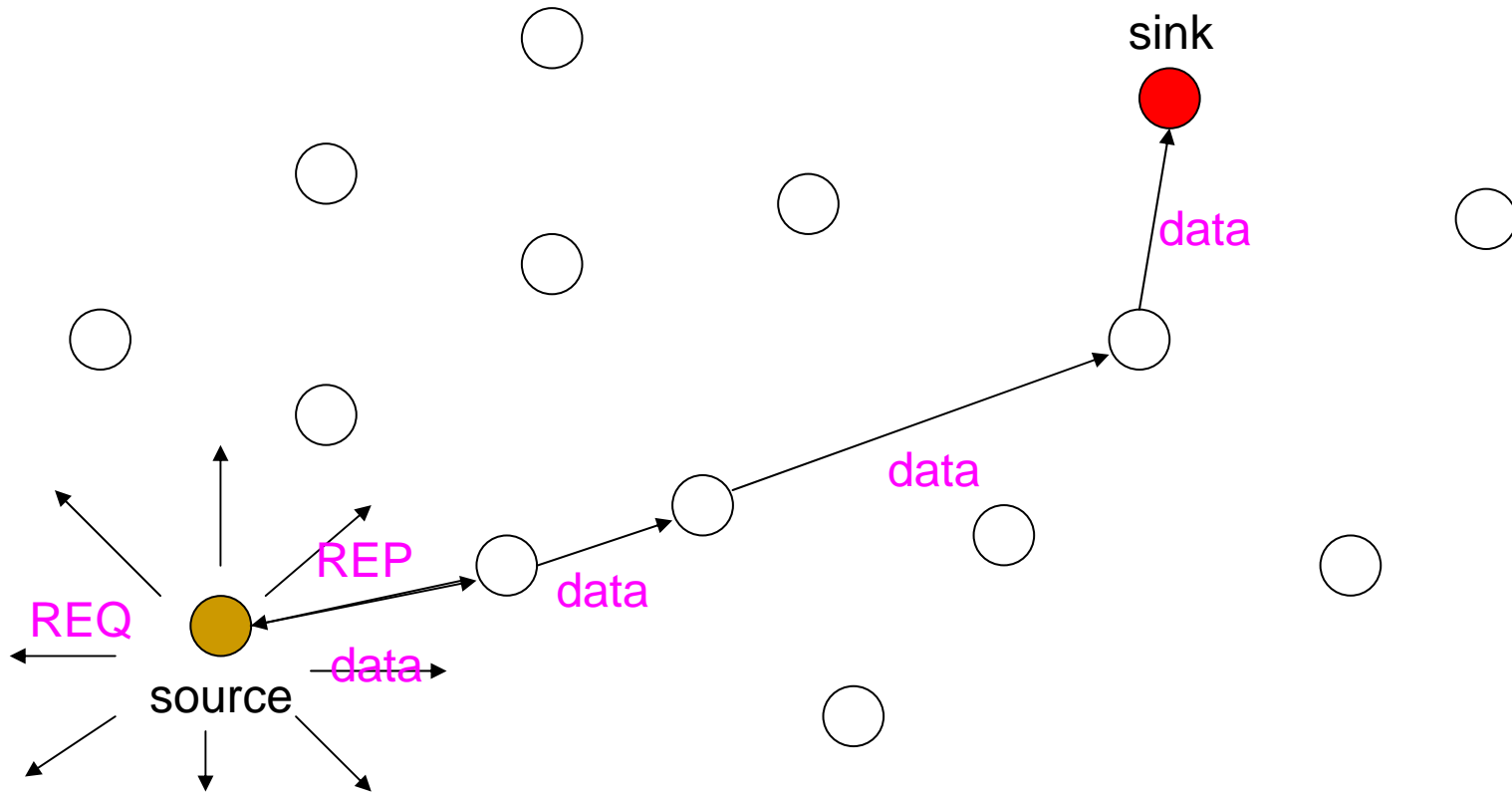
Introduction(2/2)

- Selecting next hop for data forwarding locally and without using routing tables
 - Minimizing the overhead incurred in **creating** and **maintaining** the routing paths.
- Geographical location, residual energies, and etc.

Using routing tables to forward data to sink



Event driven routing algorithms



Related work(1/2)

- GeRaF
 - Geographical method
 - Forwarding area is subdivided into a number of regions
 - Near the sink first to contend

Related work(2/2)

■ CBF

- Geographical method
- Using biased timers
- Near the sink first to send reply

■ IGF

- Geographical + residual energies methods
 - Using biased timers
 - Lower cost first to send reply
-

Cost and Collision Minimizing Routing (CCMR)

- Each node will have a cost and a token
 - Cost can be considered with geographical location, residual energies, and etc => normalized to $[0,1]$
 - Token is random picked in $[0,1]$ at every contention round
 - Tokens are used to model cost-unaware access probability
 - Costs are fully correlated => only considering tokens

Cost and Collision Minimizing Routing (CCMR)

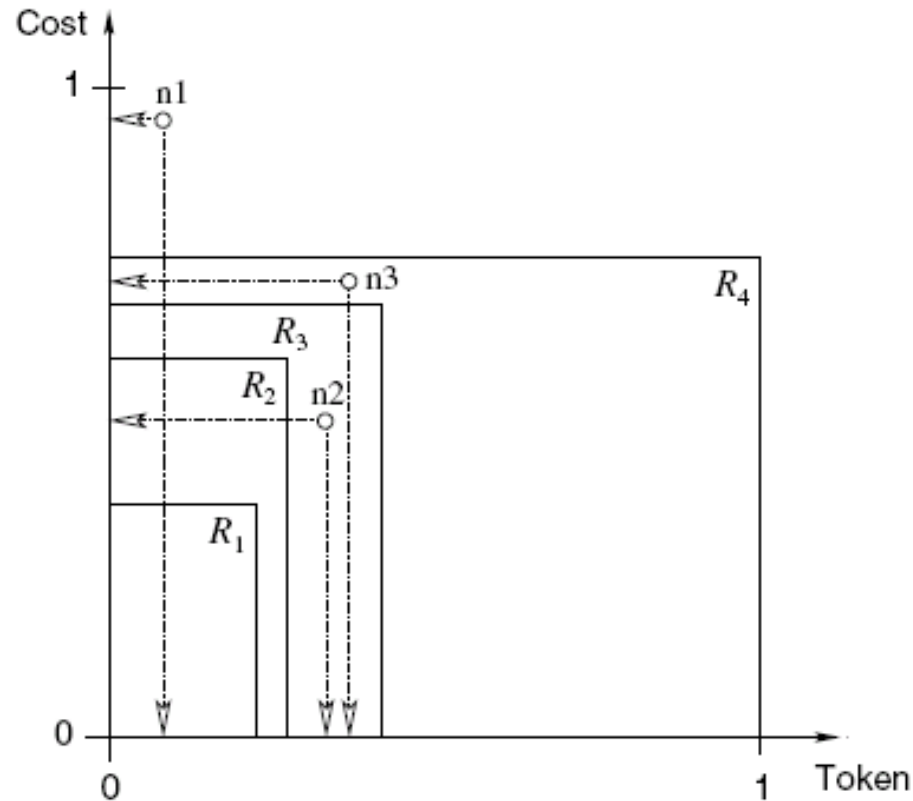


Fig. 1. Example of access regions and nodes representation for $W = 4$.

Cost and Collision Minimizing Routing (CCMR)

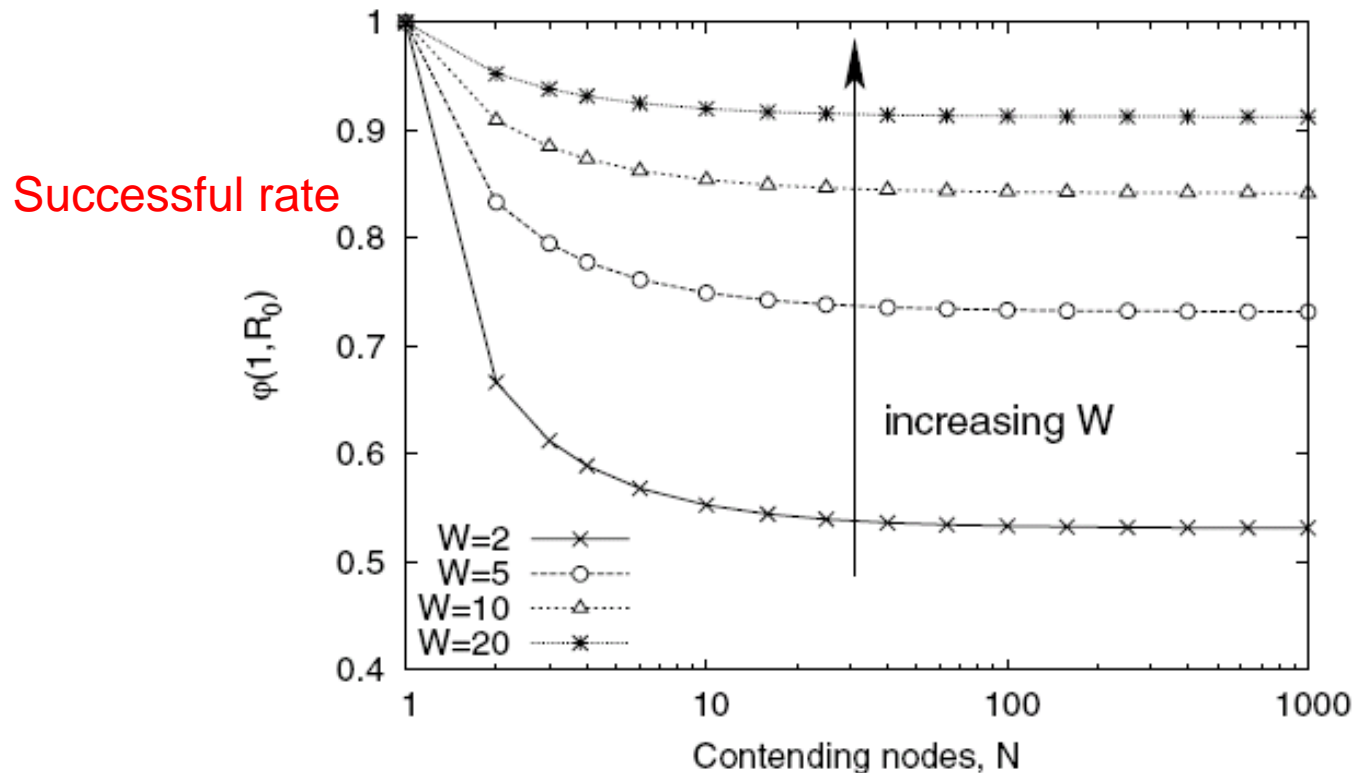


Fig. 2. $\varphi(1, R_0)$ as a function of N .

Cost and Collision Minimizing Routing (CCMR)

■ CCMR-GEO

- Only consider geographical position

$$c_n = 1 - (a_n / R)$$

■ CCMR-NRG

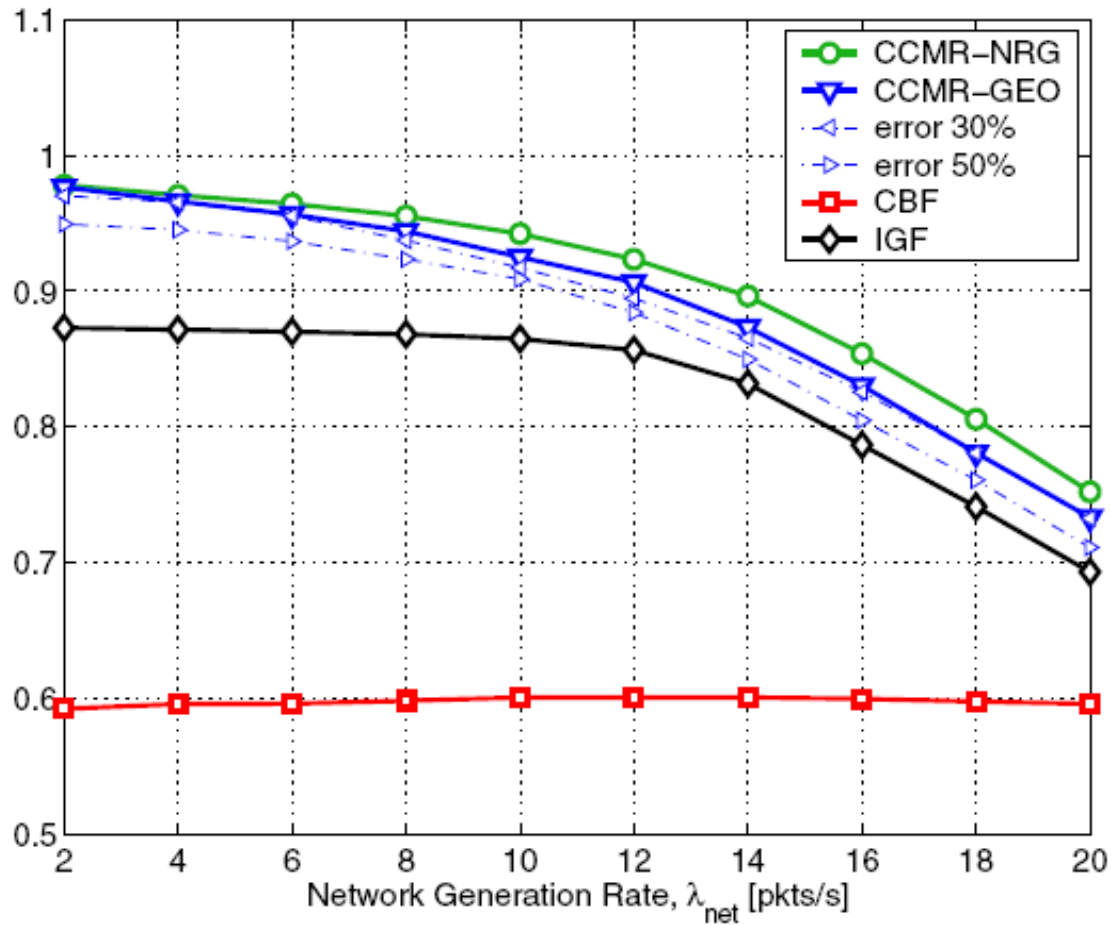
- Consider geographical position and residual energies

$$c_n = 1 - (a_n / R)(e_r / E)$$

Simulation results

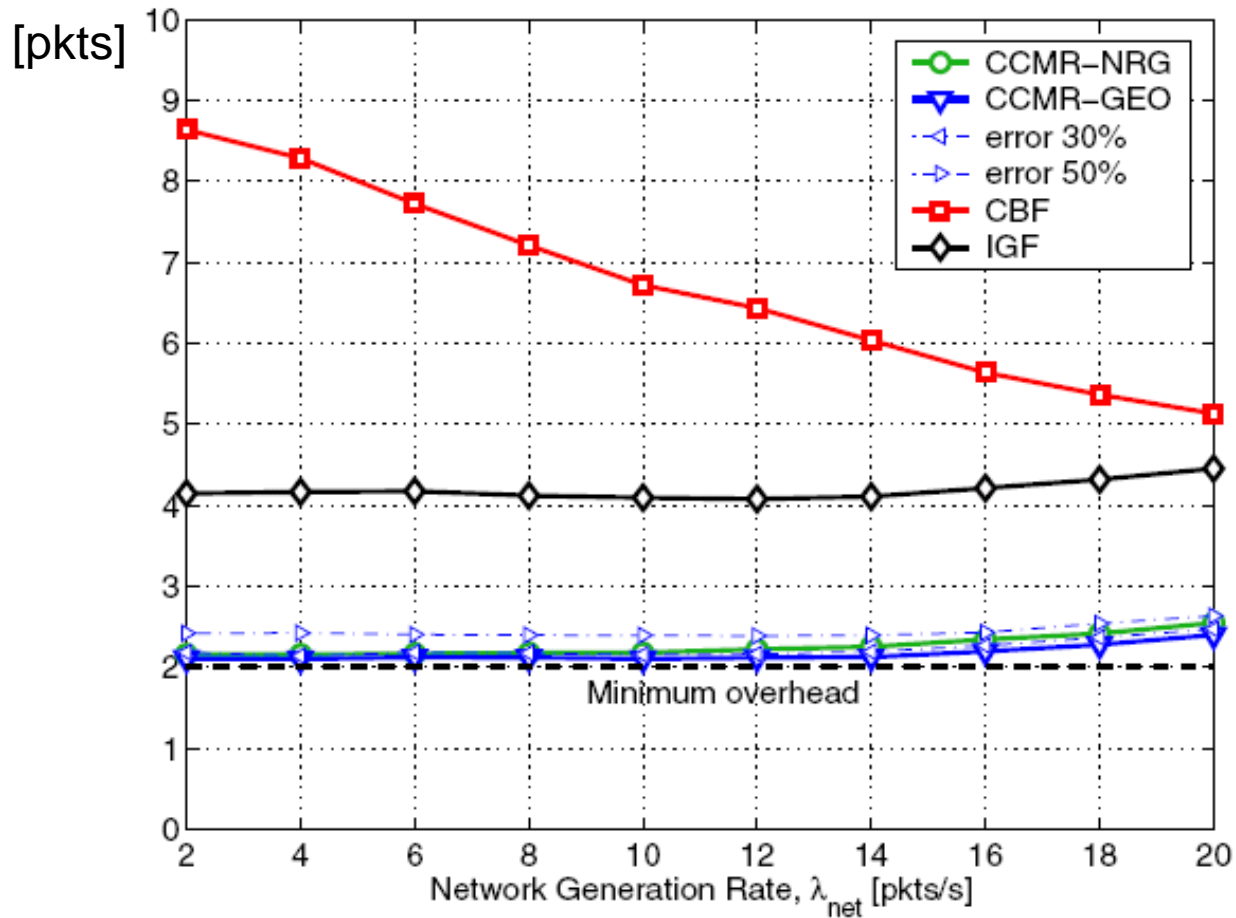
- Sensors are uniform placed within 100x100m
- Transmission range = 30m
- Bit rate = 38400bps
- Energy consumption
 - Idle = 26.1mW
 - Reception = 47.1mW
 - Transmission = 90.6mW

Delivery rate

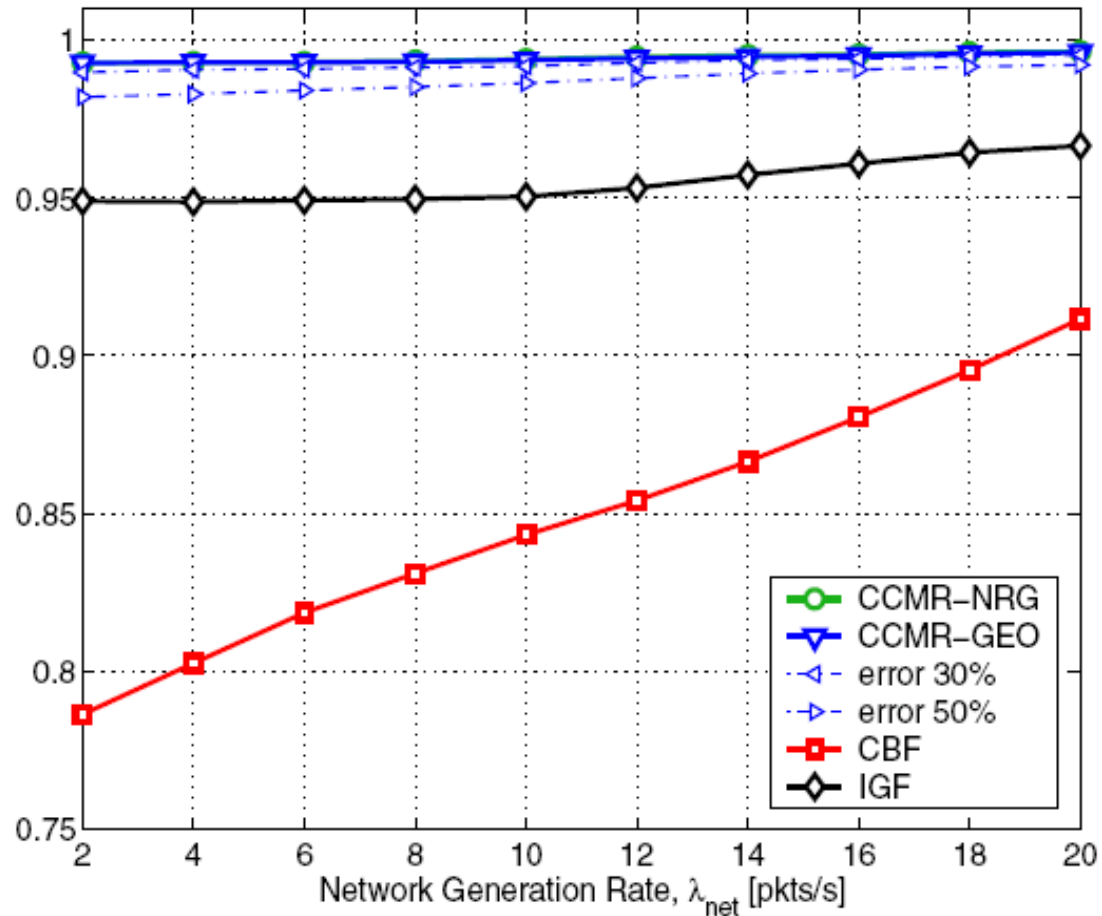


Average protocol overhead

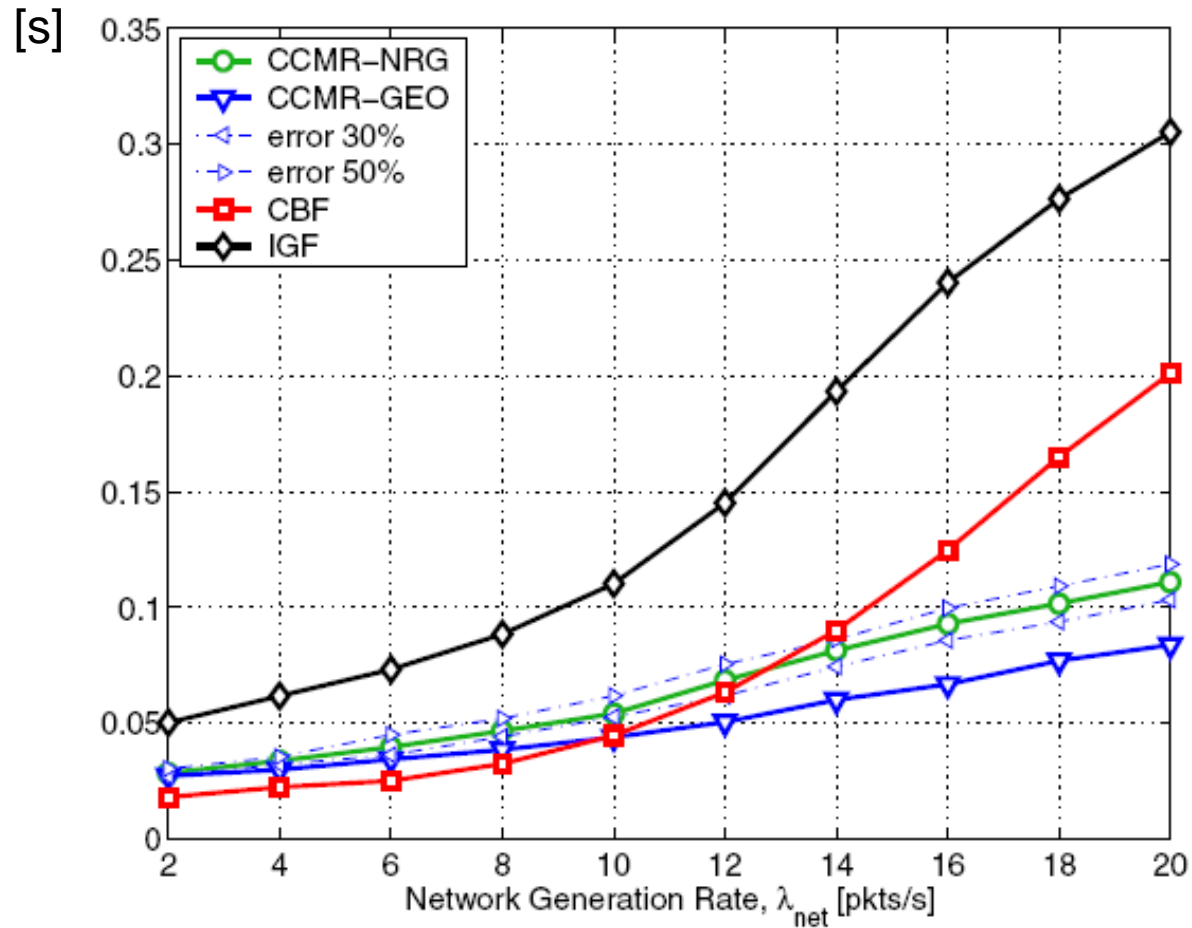
Optimal = 1 REQ + 1 REP



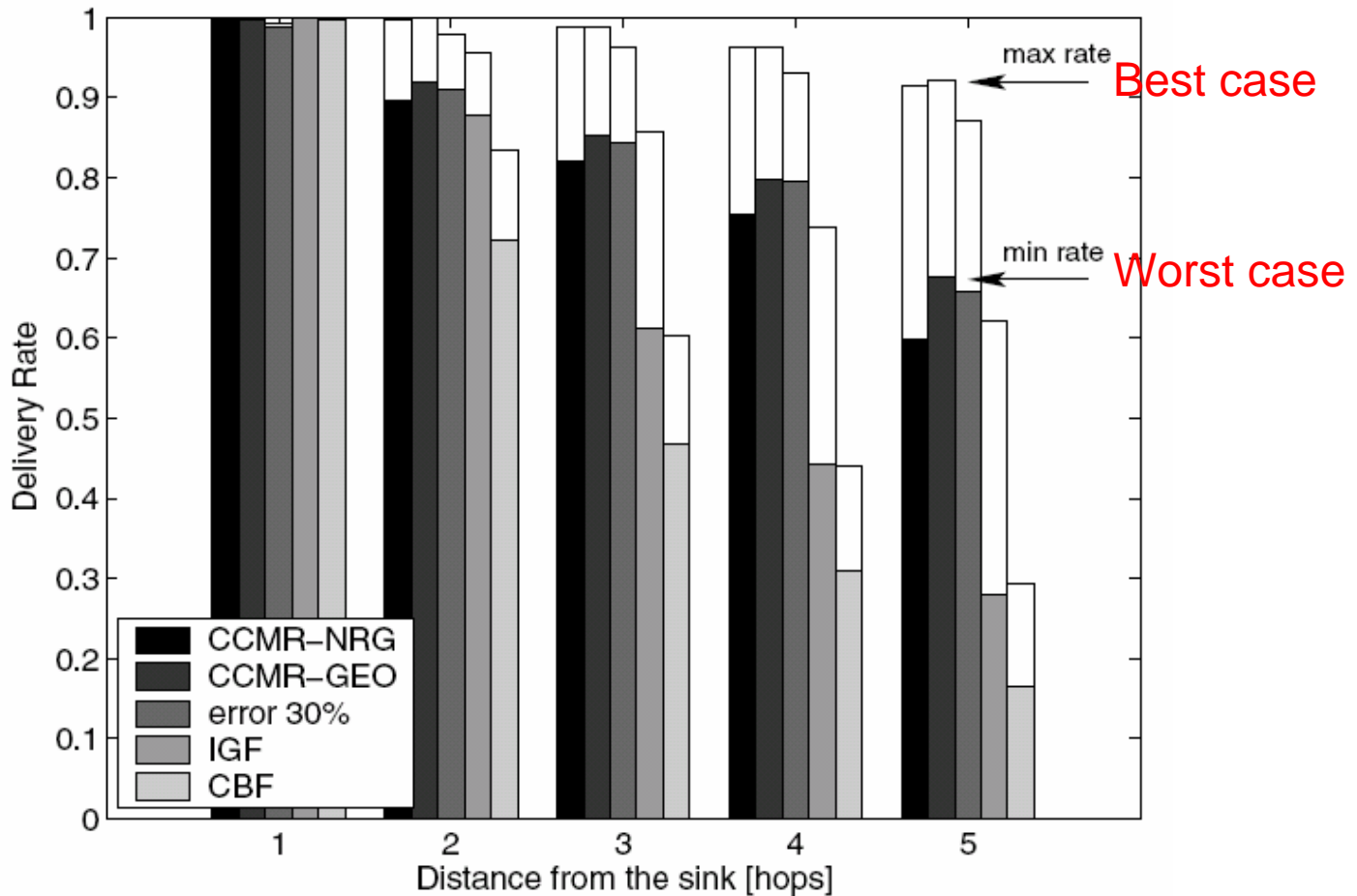
Probability of a successful contention



Duration of the channel contention



Delivery rate vs. hop distance from the sink



Conclusions

- CCMR is designed to be reactive to the network dynamics and to elect the next hop with extremely low overhead.
- The author analytically modeled the next hop selection problem by finding the optimal policy by means of a dynamic programming formulation.

Discussions

- How about routing table based algorithms?
 - Energy consumption
 - Delivery rate
 - End to end delay