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# A Passive Geographical Routing Protocol in VANET

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# Outline

- Introduction
- Related Works
- Routing Process
- Simulation and Performance Analysis
- Conclusion and Future Work

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# Introduction

- VANET have some characteristics
  - Maybe no stable infrastructures are available
  - Network topology and states may change rapidly. Nodes may perhaps have no long communication session time
  - Power and memory are not problems in VANET
  - VANET may have many building obstacles between nodes in city urban environments
- Traditional ad hoc routing protocols require high routing overhead and do not use any available information to maximize routing performance

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## Related Works

- Source routing protocol
  - Dynamic Source Routing ( DSR )
- Distance vector protocol
  - Destination Sequence Distance Vector ( DSDV )
  - Ad hoc On-demand Distance Vector (AODV )
- Position based protocol
  - Greedy perimeter stateless routing (GPSR)
    - Grid Location Service (GLS)
  - Weak State Routing (WSR)

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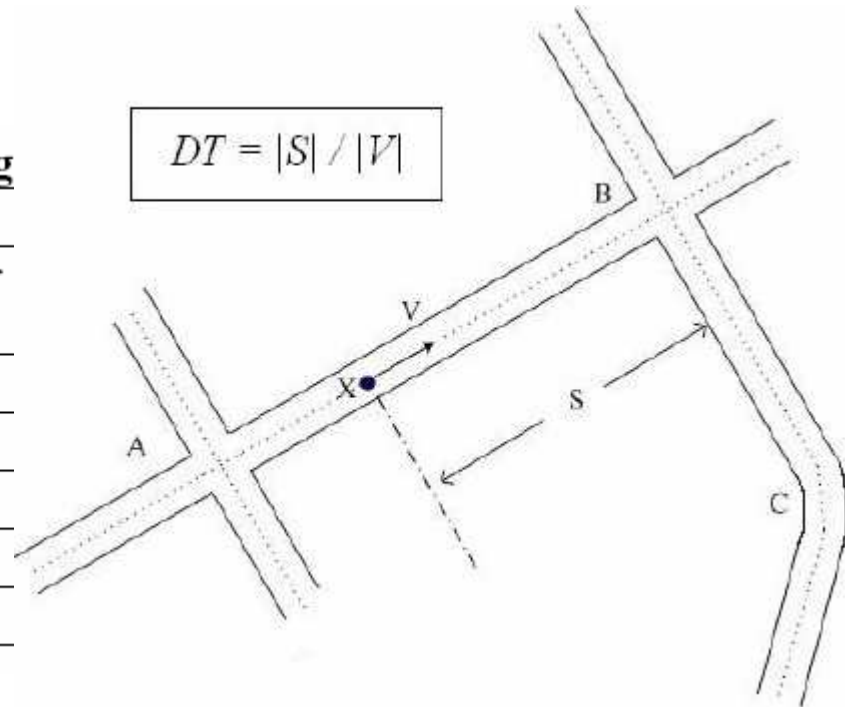
# Assumptions

- On-board GPS device
  - Position and velocity information
- City road map
  - Position prognostication
- Beacon messages
- Route announcement packet
- If source has no destination geographical Information, it simply sends packets towards its movement direction

# Geographical information local propagation ( Beacon )

**Table 1: Notation description sent in beacon message**

Notation	Description
$TS$	Local time stamp, integer variant for each node
$X$	x coordinate
$Y$	y coordinate
$V$	Velocity magnitude
$D$	Velocity direction
$DT$	Velocity direction stable duration



- DV will be used to determine the geographical information cache time by others and route announcement propagation frequency by the source

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# Geographical information remote propagation (Announcement)

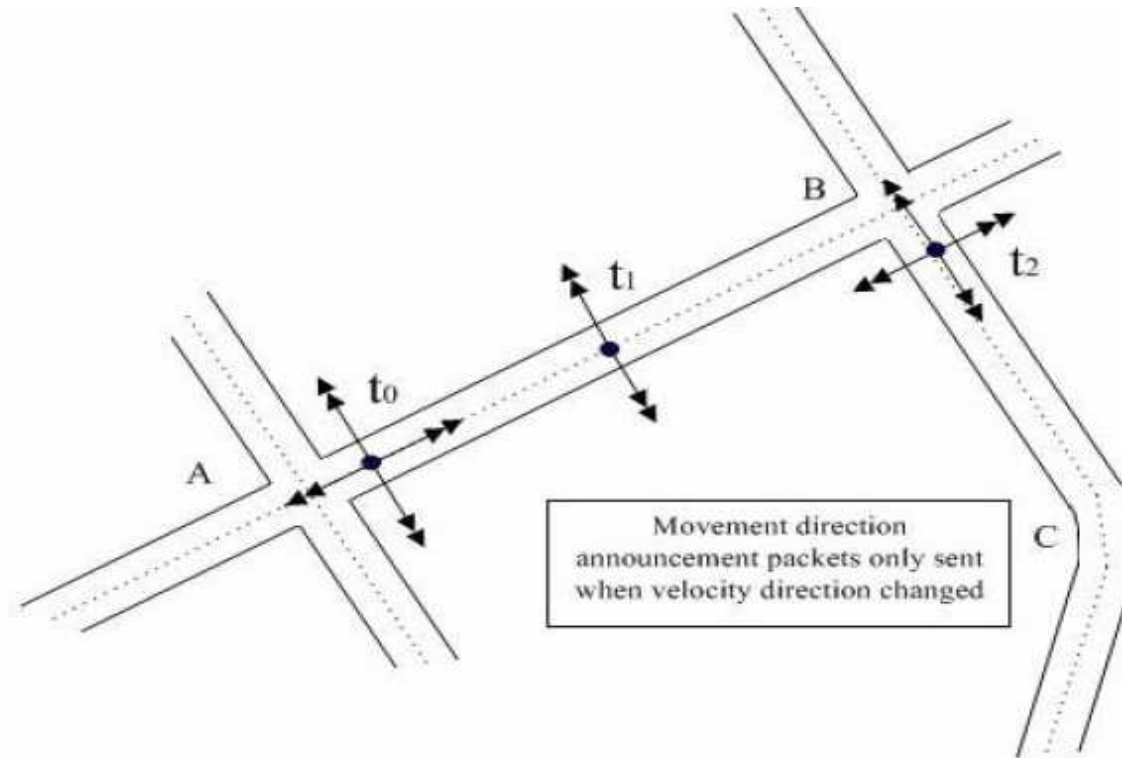
- We must have a mechanism to disseminate information to some longer distance
  - Route announcement messages
- Intermediate nodes which receive announcement packets will forward them along the direction they are sent

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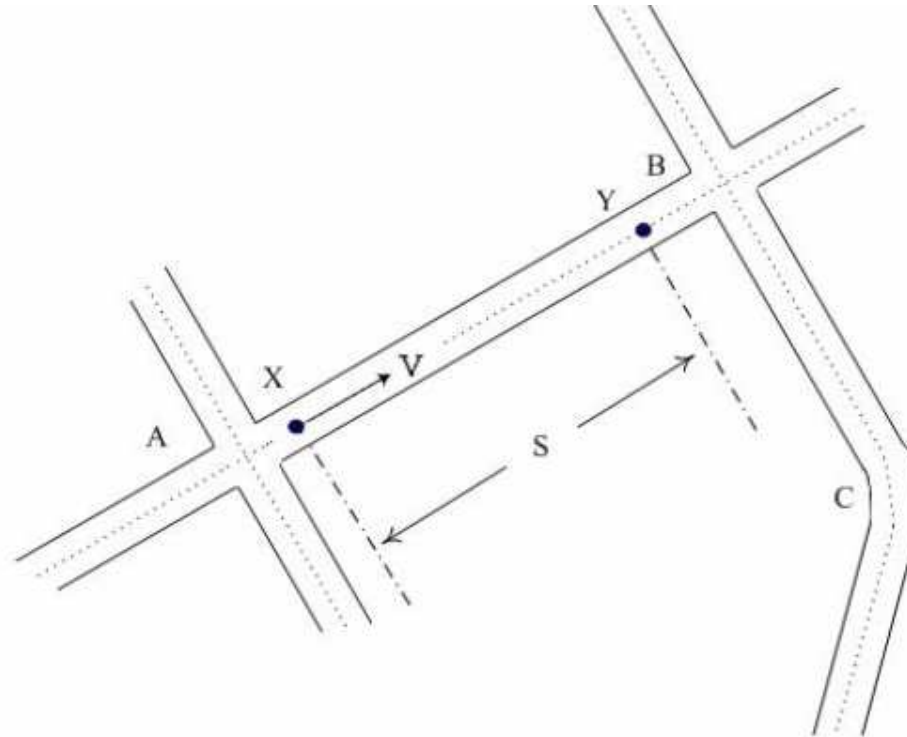
**Figure 2: Announcement sending.** Nodes send out announcement packets in 4 orthogonal directions along their velocity direction. I.e. nodes send 4 packets as 0, 90, 180, 270 degree, which 0 degree is related to their movement direction. 90 and 270 degree announcement packets will be sent periodically. Other 2 direction announcement packets will only be sent when nodes' velocity direction change.

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# Packet Forwarding

- For data packet sending, we may have destination's geographical information or not
  - Bad situation: source sends data in its movement direction. Packet forward direction can be fixed by intermediated nodes, which have destination's info.
  - Good situation: source will prognosticate destination's current location and then forward packet to the best next hop

# Location prognostication mechanism



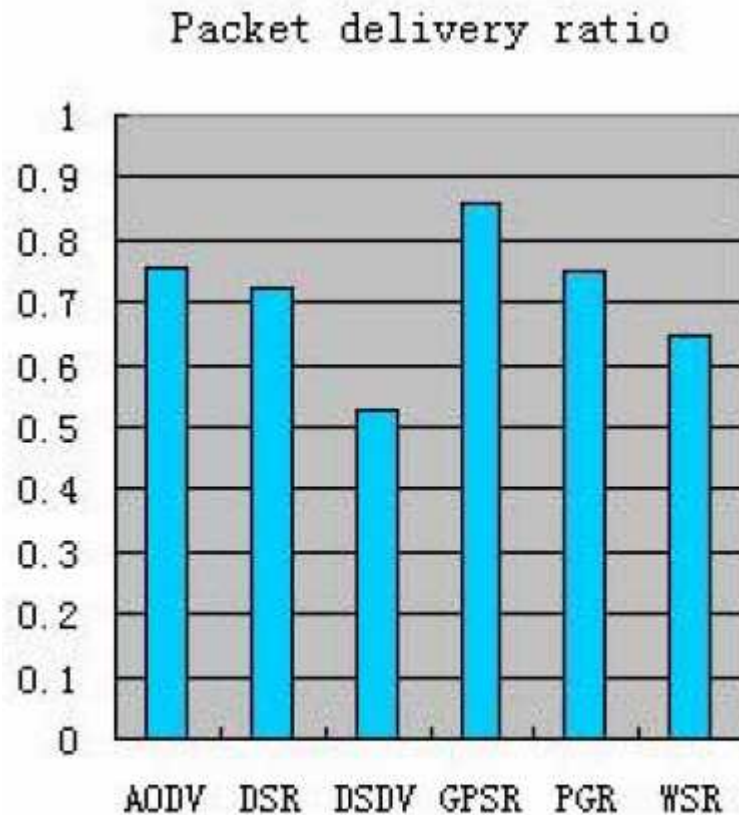
**Figure 3: location prognostication is as,  $Y = X + S$ , Node was at X at time  $t_0$ , then moves to Y at time  $t_1$ . S is defined as  $S = |V| \times \Delta T$ ,  $\Delta T = t_1 - t_0$ .**

# Algorithm for packet forwarding in PGR

## **PacketForward**(*p*)

```
1: Src <- p.Header[Source]
2: Des <- p.Header[Dest]
3: entrySrc <- RouteTable[Src.ip]
4: entryDes <- RouteTable[Des.ip]
5: //Update source's route table entry if necessarily
6: if(Src.TS > entrySrc.TS) then
7:   RouteTable[Src.ip] = Src
8: end if
9: //Update destination's route table entry, or packet header
10: if(Des.TS > entryDes.TS) then
11:   RouteTable[Des.ip] = Des
12: else
13:   p.Header[Dest] = RouteTable[Des.ip]
14: end if
15: // Prognosticate dest new location
16: DestLocation <- Prognosticate(Des.ip)
17: //Find nearest next hop
18: Nexthop <- FindNearestNexthop(DestLocation)
19: SendPacket(Nexthop)
```

# Simulation and performance analysis

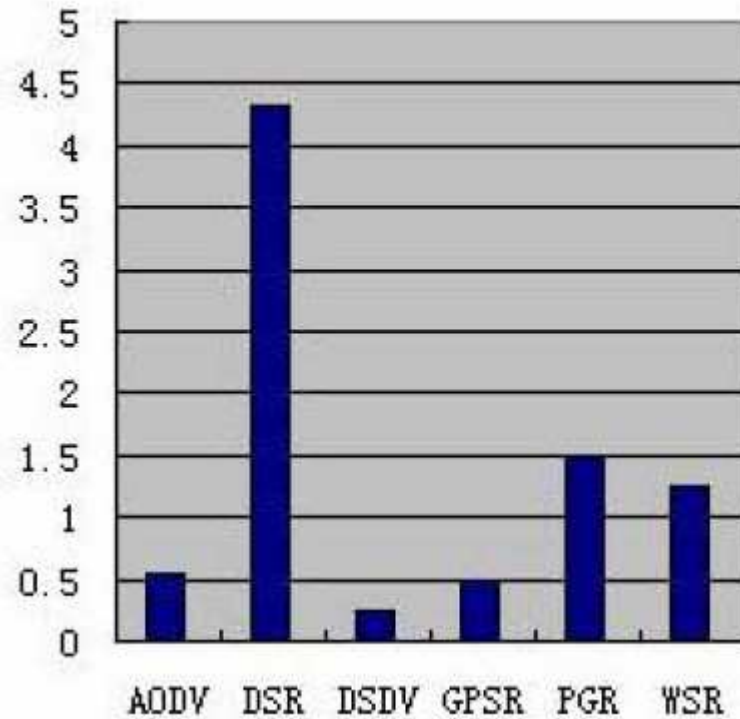


Network Simulator (NS2)  
Topology :20Km \* 20Km  
Data packet : 512 bytes  
Number: 100 vehicles  
Simulation time :180 seconds

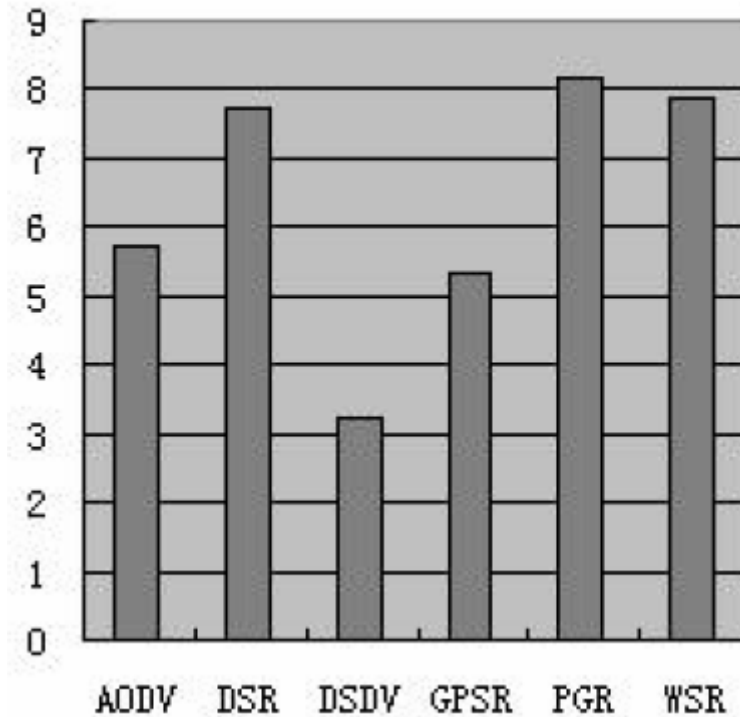
**Figure 4. Packet delivery ratio**

# Simulation and performance analysis

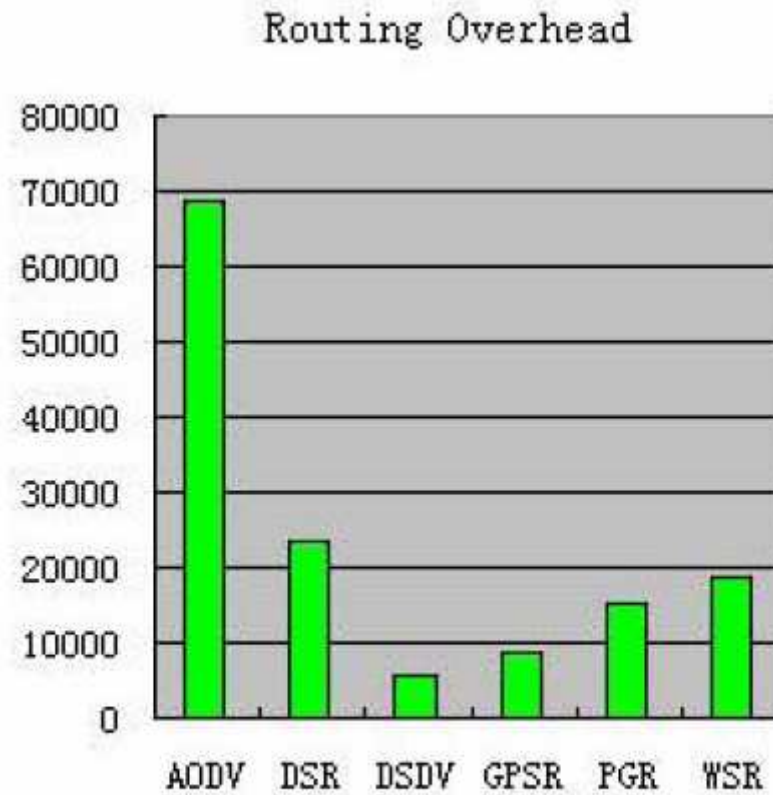
Average End to End Delay



Average Hop Count



# Simulation and performance analysis



**Figure 7. Routing Overhead**

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# Conclusion

- The algorithm does not assume a global location query service system to be pre-deployed, which is most of the practical case in VANET environments
- PGR provides high data packet delivery ratio in high dynamic topology of VANET with lower overhead comparing to the traditional routing protocols



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## Future work

- In realistic urban environment , there may be many obstacles such as buildings and trees along the street, which make communication of nodes in adjacent streets impossible
- Some nodes are isolated when they go far from others, which makes the network many sub-networks. We may change out algorithm to adapt to DTN