

# Node Stability-Based Location Updating in Mobile *Ad-Hoc* *Networks*

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# OUTLINE

- Introduction
- Two types of Location Updating
- Assumption
- Algorithm
- *Simulation*

# Introduction

- the nodes are mobile, which renders the network topology in MANETs susceptible to change with time.
- In the *conventional location updating algorithm*, each node periodically broadcasts a Hello packet and it updates its Neighbor Table on receiving the acknowledgment from the node.

# Introduction

This algorithm improves:

1. less number of acknowledgments is transmitted in maintaining the Neighbor Table;
2. less number of collisions takes place;
3. less updating is required to maintain the Neighbor Table;

# Two types of Location Updating

- Updating this information when the network layer requires
  - The **overhead** involved in the periodic updating of the Neighbor Table is **not involved** in this case.
  - Updating of the Neighbor Table , on demand, **causes a delay**.

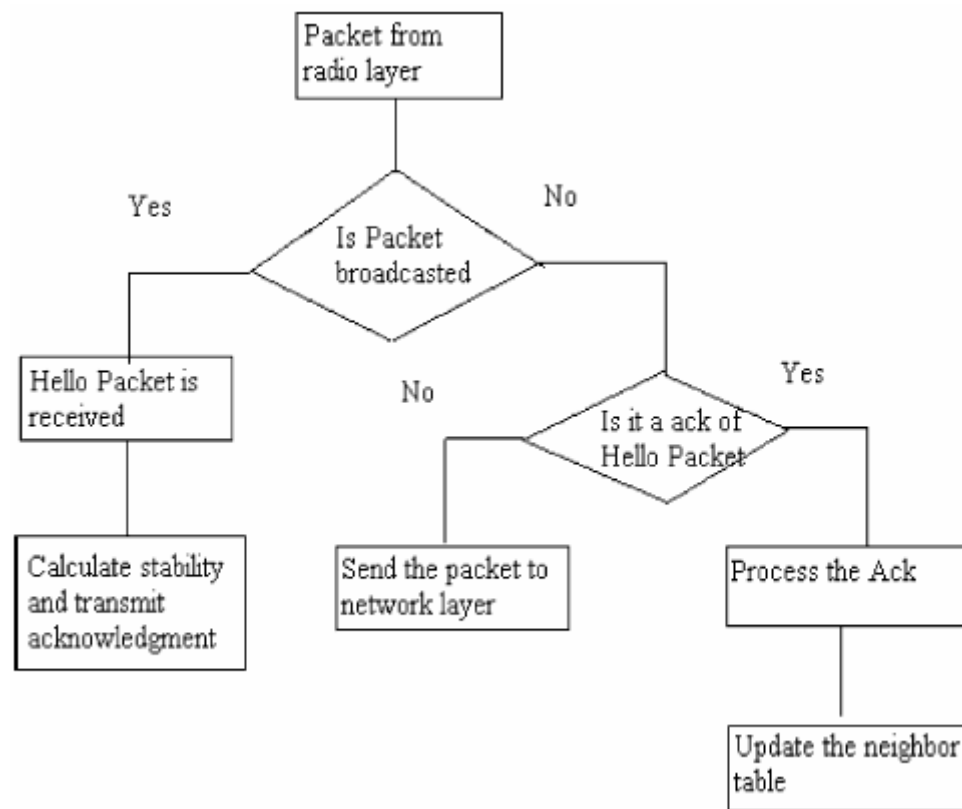
# Two types of Location Updating

- Updating the Neighbor Table periodically
  - When the routing table requires the Neighbor Table, it can be provided **without much delay**.
  - The periodic updating of the Neighbor Table **causes a lot of traffic** on the network.

# Assumption

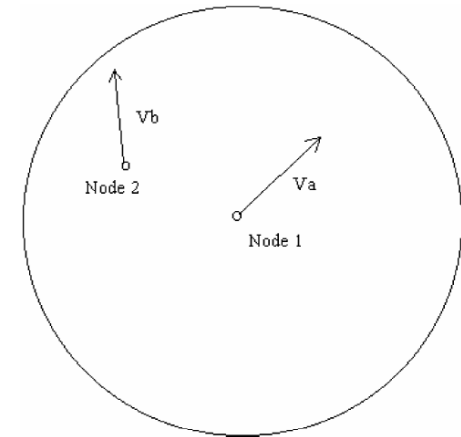
- each node knows its location using Global Positioning System (GPS);
- each node knows its current velocity vector (a node can use GPS and a clock for this);
- each node has an omni-directional antenna;
- each node has enough computational power;
- each node knows the time for which it can stay switched-on

- the processing of packets in the proposed algorithm

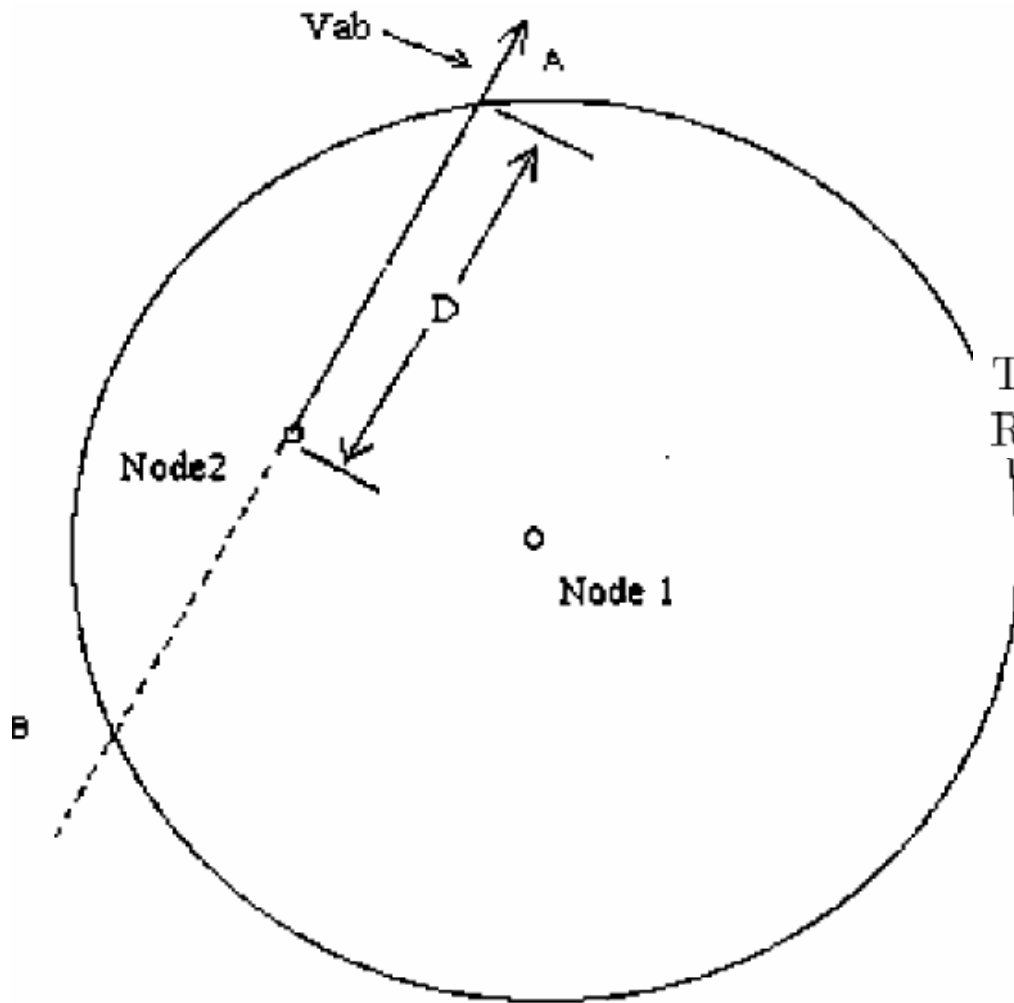




# Algorithm



- **Stability:**
- *How close the node A is to the boundary of the transmission range of node B. The closer the nodes A and B are, the more stable will be the node A.*
- *Battery backup of A. If the time remaining for which the node can stay powered up is very less, the stability of A will decrease. This is because A can die out any time.*



$$K_f = D / (T * V_{ab}).$$

$$K = \tan^{-1}(K_f).$$

T: The retransmission time of Hello packet.  
 R: Transmission range of Node 1

- ***Retransmission Time*** is dependent on the minimum value of the stability factor of its neighbors

### Steps to Initialize

1. Set  $T = T_1$ .
2. Set  $LK = K_2$ , where LK is the limiter K.

### Steps to Send Hello Packets

Do the following and send the Hello packet after every  $T$  seconds.

1. If there are no neighbors then

$LK = \text{next } K \text{ in } K_{\text{recv}} \text{ list,}$

Else

Set  $LK = K_2$ .

2. Mark all neighbors having  $K_{\text{recv}} \leq LK$ .
3. Fill in the current Hello packet with the following information of the node:
  - (a) GPS coordinates.
  - (b) Velocity Vector.
  - (c) Range.
4. Wait for the acknowledgments till “time out” interval.

5. Do the following according to the appropriate situation:

(a) For a node which is marked and does not send acknowledgement, remove it from the Neighbor Table.

(b) For a node which is not marked, but exists in the Neighbor Table, send an acknowledgement and update its  $K_{\text{recv}}$ .

(c) For a node that does not exist in the Neighbor Table, send an acknowledgement (implying that it is a new node). Enter its  $K_{\text{recv}}$  from the acknowledgement and set  $K_{\text{send}} = 0$  in the Neighbor Table entry corresponding to this node.

6. According to the minimum value of  $K_{\text{recv}}$ , modify the retransmission time  $T$ .

### Steps taken when a node receives a Hello packet

1. Calculate  $K$  on the basis of the battery backup of the receiving node and the following information sent in the Hello packet:

- (a) GPS.
- (b) Velocity Vector.
- (c) Range.

2. Compare  $LK$  with  $K$ .

3. If  $LK \geq K$  or  $LK \geq K_{\text{send}}$  then

{

Update  $K_{\text{send}}$  entry corresponding to the transmitter node.

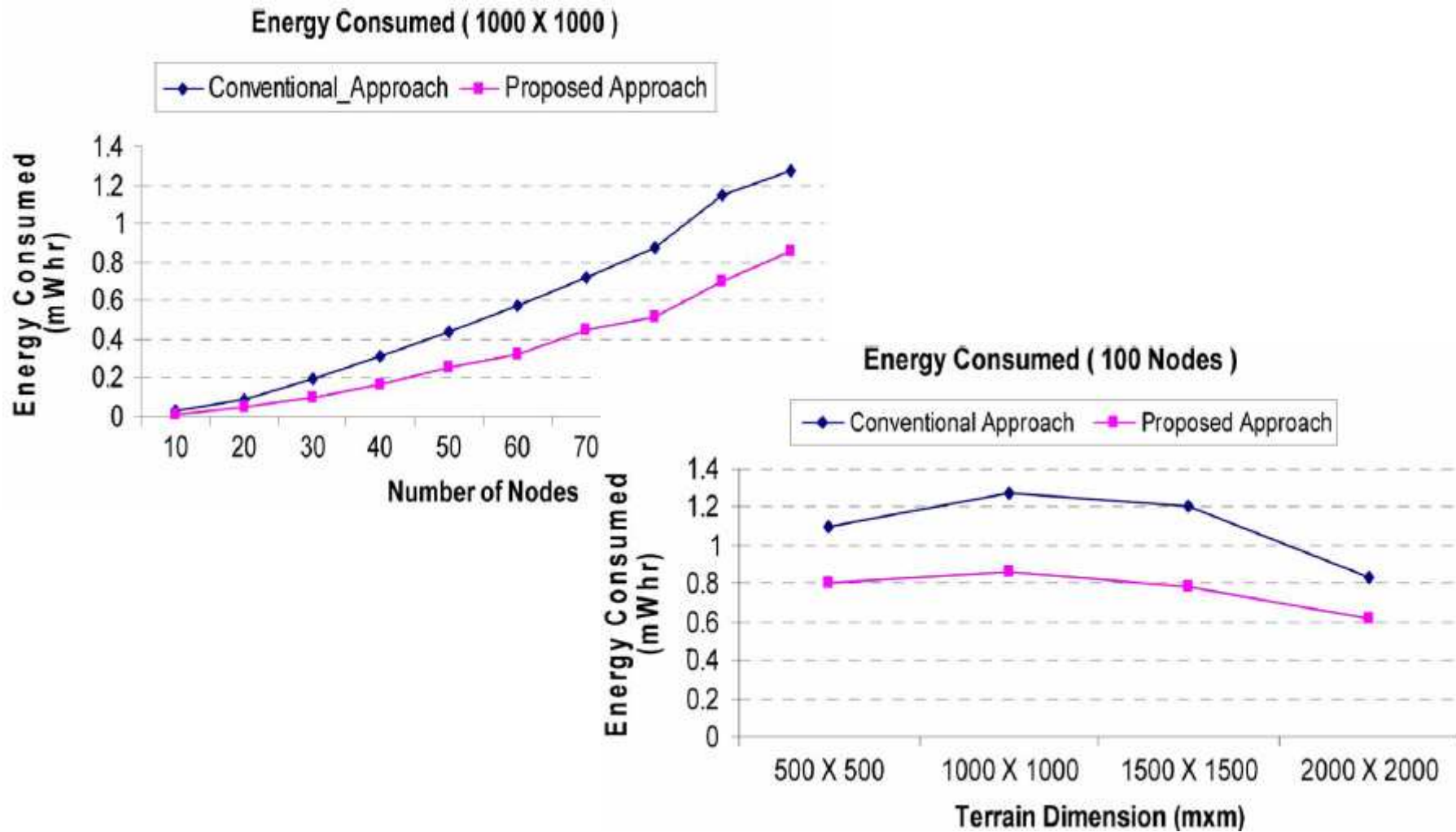
Send acknowledge with  $K$ .

}

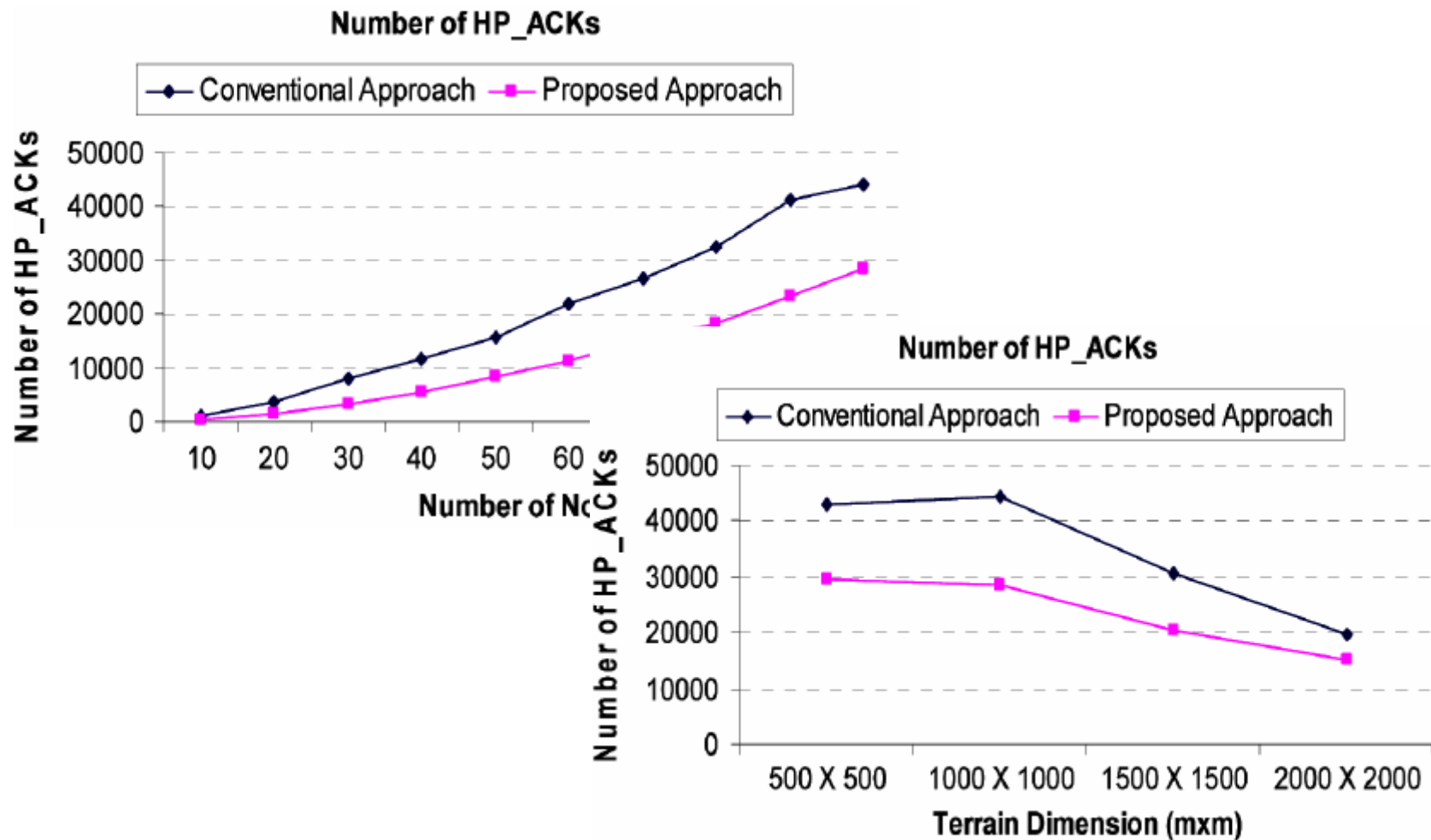
Else

Ignore the Hello packet.

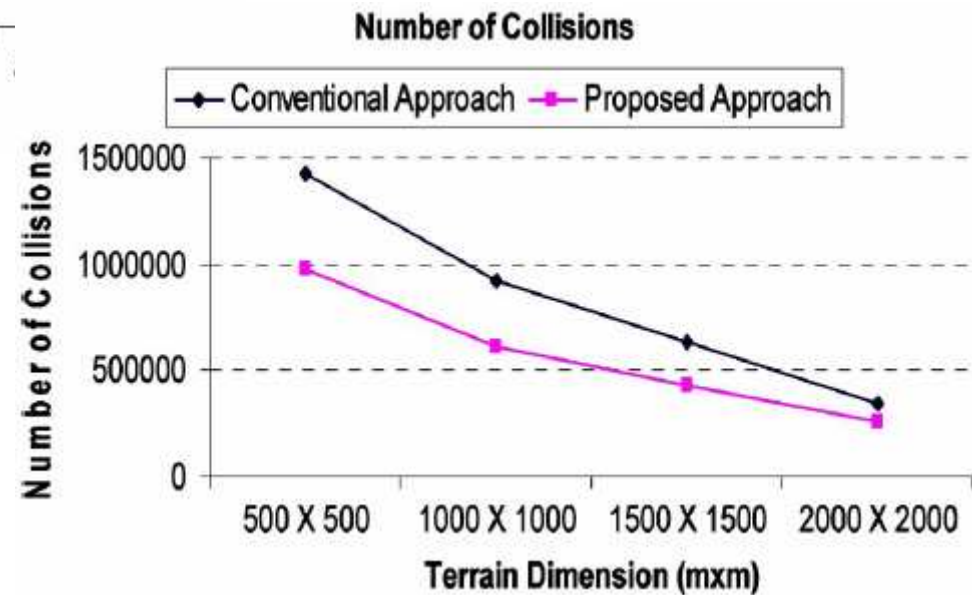
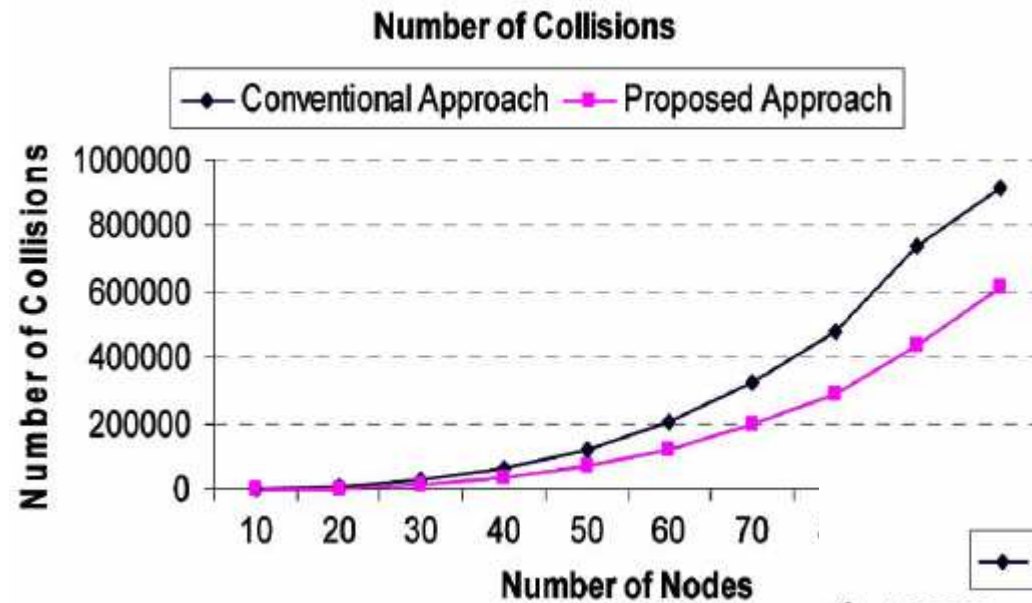
# Simulation- energy consumed



# Simulation- number of Hello packet acknowledgements



# *Simulation- number of collisions*





# CONCLUSION

- The main focus of the proposed algorithm is to **reduce the number of acknowledgment packets** by varying the updating information of less stable nodes more frequently compared to the more stable nodes.
- The performance of this algorithm was tested on the following parameters:
  - number of Hello packet acknowledgements transmitted;
  - energy consumed;
  - number of collisions.